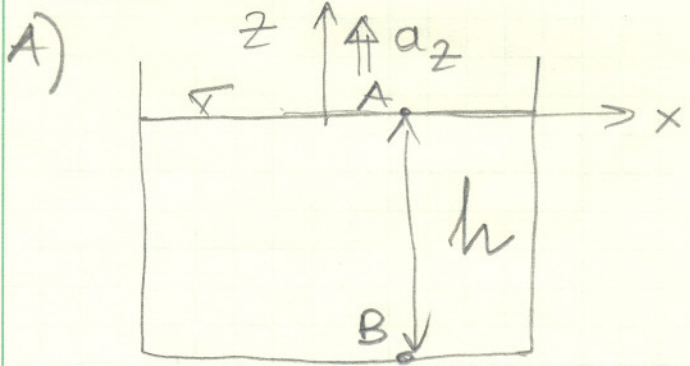


$$-\frac{\partial(p+\gamma z)}{\partial z} = \rho a_e \quad 4.17, \text{ Euler equ.}$$



$$-\frac{\partial(p+\gamma z)}{\partial z} = \rho a_z \rightsquigarrow$$

$$-\frac{\partial}{\partial z}(p+\gamma z) = \frac{\partial}{\partial z}(\rho a_z z) \rightsquigarrow$$

$$\rightsquigarrow -\frac{\partial}{\partial z}[p+\gamma z + \rho a_z z] = 0 \rightsquigarrow$$

$$\rightsquigarrow p + \gamma z + \rho a_z z = \text{const.} \rightsquigarrow \boxed{p + \rho(g + a_z)z = \underline{\underline{\text{const}}}}$$

Compare with hydro-static law $p + \gamma z = p + \rho g z = \underline{\underline{\text{const}}}$

$$p_B + \rho(g + a_z)z_B = p_A + \rho(g + a_z)z_A$$

$$p_B = p_A + \rho(g + a_z)(z_A - z_B)$$

\uparrow
 h

$$\rightsquigarrow p_B = \underline{\underline{\rho(g + a_z)h}}$$

Compare with hydrostatic law:

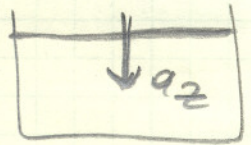
$$p_B = \underline{\underline{\rho g h}}$$

So, hydro-law can be modified

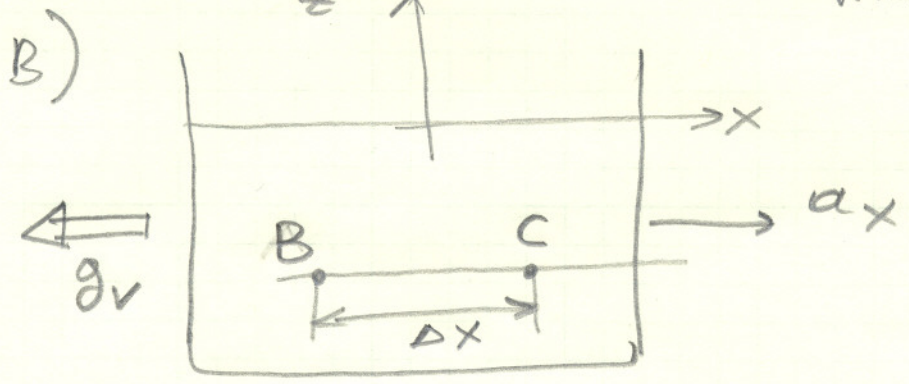
so that $g_{v,z}$ (virtual accel. of gravity) = $\underline{\underline{g + a_z}}$

what would happen if a_z points down?

$$P_B = \rho (g - a_z) h$$



what if $a_z = g$?



$$-\frac{\partial(P + \rho z)}{\partial x} = \rho a_x \quad \text{or} \quad -\frac{\partial(P)}{\partial x} = \rho a_x \quad \text{or}$$

$$-\frac{\partial P}{\partial x} = \frac{\partial(\rho a_x x)}{\partial x} \rightsquigarrow -\frac{\partial}{\partial x} [P + \rho a_x x] = 0$$

$$\rightsquigarrow P + \rho a_x x = \text{const. (for each } z)$$

$$\underline{\text{Ex.}} \quad P_B + \rho a_x x_B = P_C + \rho a_x x_C \rightsquigarrow$$

$$\rightsquigarrow P_B = P_C + \rho a_x (x_C - x_B) \rightsquigarrow$$

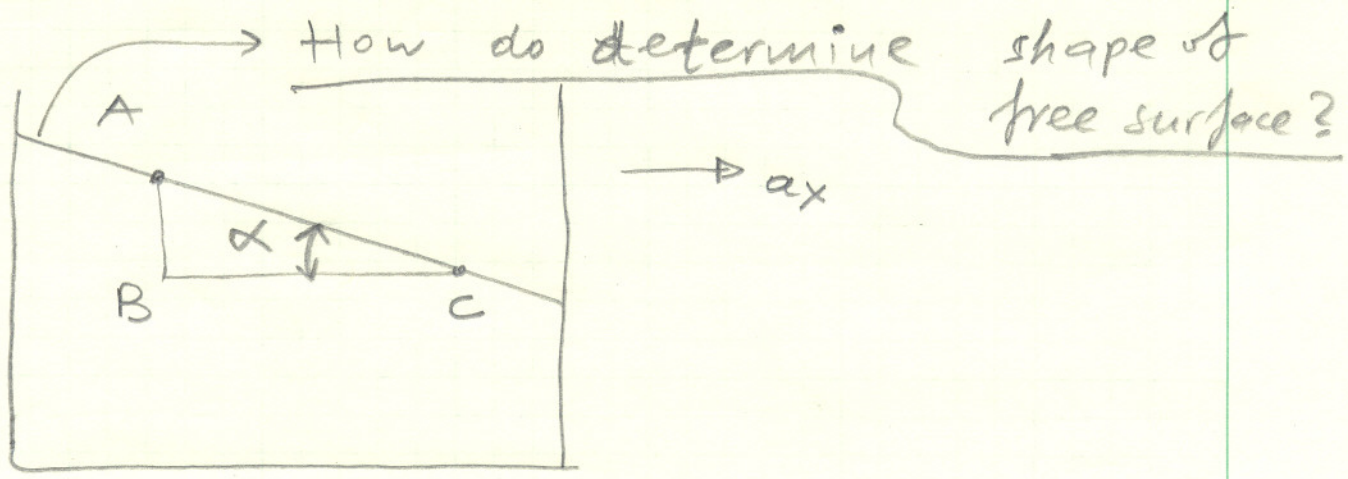
$$\rightsquigarrow P_B = P_C + \underline{\underline{\rho a_x \Delta x}}$$

The above looks like hydro-law along x where $g_{v,x} = a_x$ and in opposite direction.

Along z : $-\frac{\partial(P+\gamma z)}{\partial z} = 0$ (if we only have a_x , but $a_z=0$)

$\Rightarrow P+\gamma z = \text{const.}$ for const. x

So, hydrostatic law still applies on the same vertical



$P_B = P_A + \rho g (AB)$ (1)

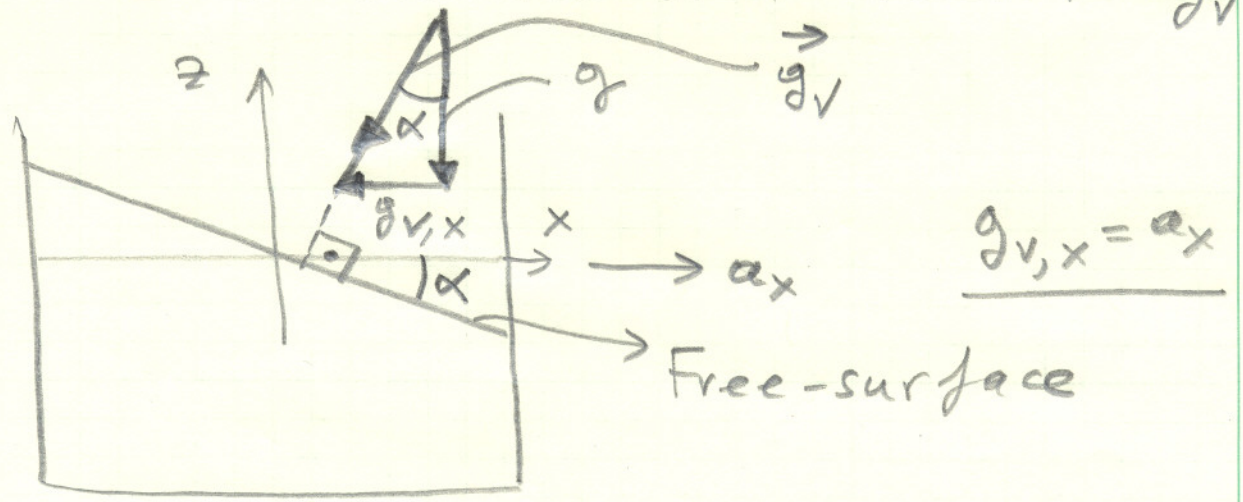
$P_B = P_C + \rho a_x (BC)$ (2)

Equating the RHS's of (1) and (2) we get: $P_A + \rho g (AB) = P_C + \rho a_x (BC)$ (3)

On the free surface $P_A = P_C = 0$, and thus (3) becomes:

$\rho g (AB) = \rho a_x (BC) \rightarrow \frac{AB}{BC} = \frac{a_x}{g} = \tan \alpha$

The above angle α can also be determined by using the virtual acceleration vector \vec{g}_v



Free-surface must be normal to \vec{g}_v as shown in the figure above.

From geometry $\rightarrow \tan \alpha = \frac{g_{v,x}}{g} = \frac{a_x}{g}$

c) If $a_x \neq 0$ and $a_z \neq 0$

