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VISVE – A VIScous Vorticity Equation model applied to cylinders, hydrofoils and propellers in wetted and cavitating condition Lu Xing, Chunlin Wu, Zhihao Li, and Spyros A. Kinnas Ocean Engineering Group, The University of Texas at Austin

> 2-D hydrofoils in cavitating flow

The cavitation mixture model assumes that the bubble-liquid flow under investigation is a single fluid with homogeneous mixture of two phases. Therefore, only one set of equations is needed to simulate the cavitating flows. Besides the vorticity equation there are two more equations to govern the mixture.

$$\frac{\partial \alpha}{\partial t} + \vec{\nabla} \cdot (\alpha \vec{u}) = R, \qquad \vec{\nabla} \cdot \vec{u} = R\rho_l \left(\frac{1}{\rho_l} - \frac{1}{\rho_v}\right)$$

Where α is the vapor volume fraction The net phase change rate R is modeled based on Rayleigh-Plesset equation

$$\frac{P_B(t) - P_\infty(t)}{\rho_l} = R \frac{d^2 R}{dt^2} + \frac{3}{2} \left(\frac{dR}{dt}\right)^2$$

Re= 10,000 σ = 0.4 NACA0015



> Cylinders in alternating flow



Applications

 $\frac{4\nu_l}{R}\frac{dR}{dt} + \frac{2S}{\rho_l R}$



- condition, and flow around 3-D risers.

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[2] Ye Tian. Leading Edge Vortex Modeling and its Effect on Propulsor Performance. PhD Ocean Engineering Group, The University of Texas at Austin, 2014. thesis, [3] Zhihao Li, VISVE, Applied to Unidirectional and Alternating Flow around a Cylinder – Improved Results, MS thesis, Ocean Engineering Group, The University of Texas at Austin, *May 2017.*

Applications

Conclusions and Future work

• VISVE is capable of predicting flow around cylinders, 2-D and 3-D hydrofoils subjected to uniform or alternating flow with satisfactory accuracy.

• With both Open-MP and MPI parallelization implemented in the code, VISVE model is proved to be computationally efficient and spatially compact.

• VISVE is being extended to predict cavitating flow. Attention is currently focused on 2D sheet cavity. Once the model is well validated, it could be able to predict bubble or cloud cavitation without much modification.

• In the future, VISVE will be improved to handle more applications. Our next goal is to model the tip gap flow in ducted propellers, propellers in backing

References