

Ocean Engineering Group (OEG)/EWRE

(August 24, 2017)

Spyros A. Kinnas

Professor and Director of OTRC's UT Office
(Offshore Technology Research Center)

(Google: Kinnas Home Page – check courses and
OE Theses/Dissertations)

Research in the area of **computational hydrodynamics** with applications on the prediction of performance and design of high-speed marine **propulsors** or **turbines**, modeling of **cavitating** or **separated flows**, and **wave/body interaction**.

Teaching:

- **CE358: Introductory Ocean Engineering (Fall '17 - 11-12:30, Tu & Th)**
- **CE319F: Elementary Fluid Mechanics**
- **CE380P.4: Boundary Element Methods (Fall '17 - 12:30-2:00, Wed & Fri)**
- **CE380T: Computational Environmental Fluid Mechanics (Spring'18 – tent.)**
- **CE397-32: Theory of Propellers and Turbines (Fall '18 – tent.)**

Facilities:

- **CHL (Computational Hydrodynamics Laboratory) in ECJ 8.502**

Fuel-Efficient marine propulsors ...

Must comply with new EEDI (Energy Efficiency Design Index) regulations on CO₂ emissions from newly built ships



Contra-rotating props



Ducted prop

...and some water-turbines (used to generate energy from ocean currents)

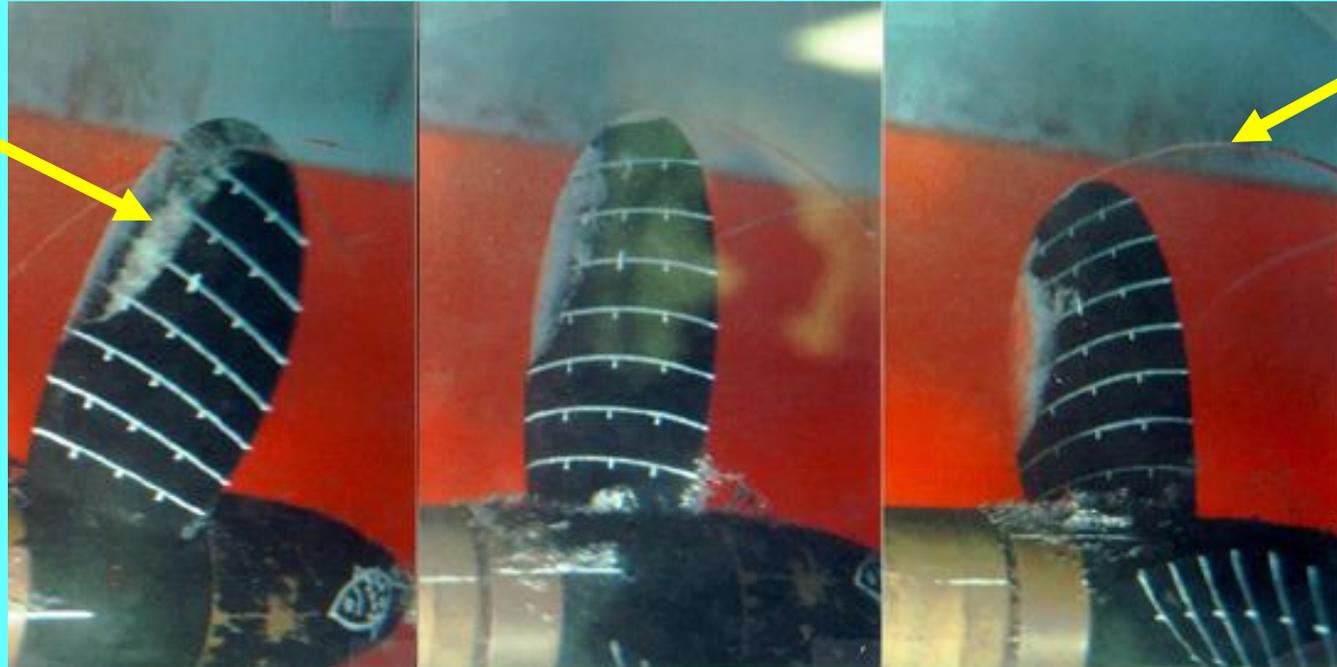


**Twin turbines (each 0.6 MW)
pulled out of the sea for
maintenance**



For high-speed propellers **cavitation** is often inevitable

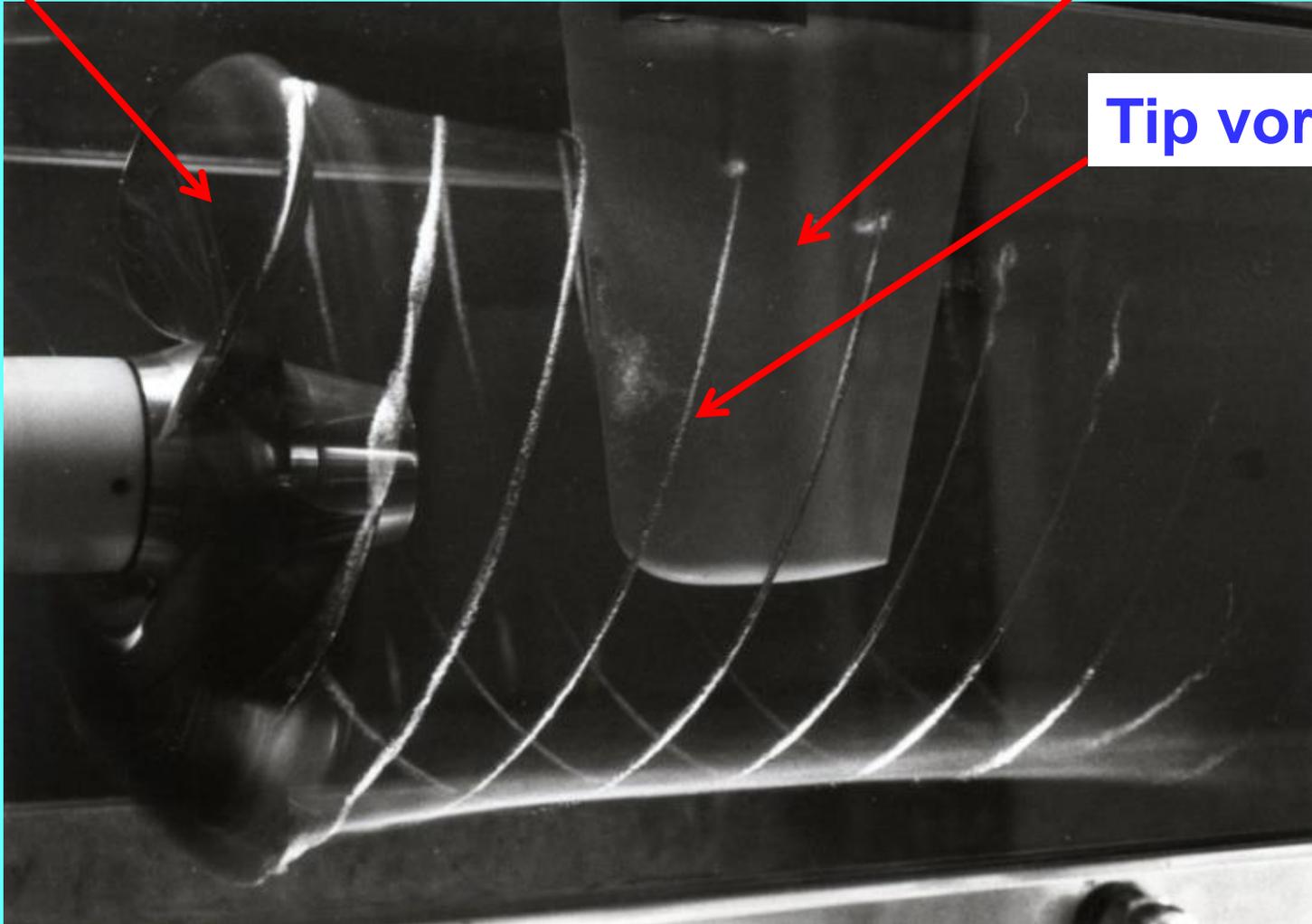
Sheet
Cavity



Tip vortex

- Cavitation can accelerate erosion of blades, produce noise, or result in sudden loss of thrust
- However, allowing for some cavitation can **increase efficiency**

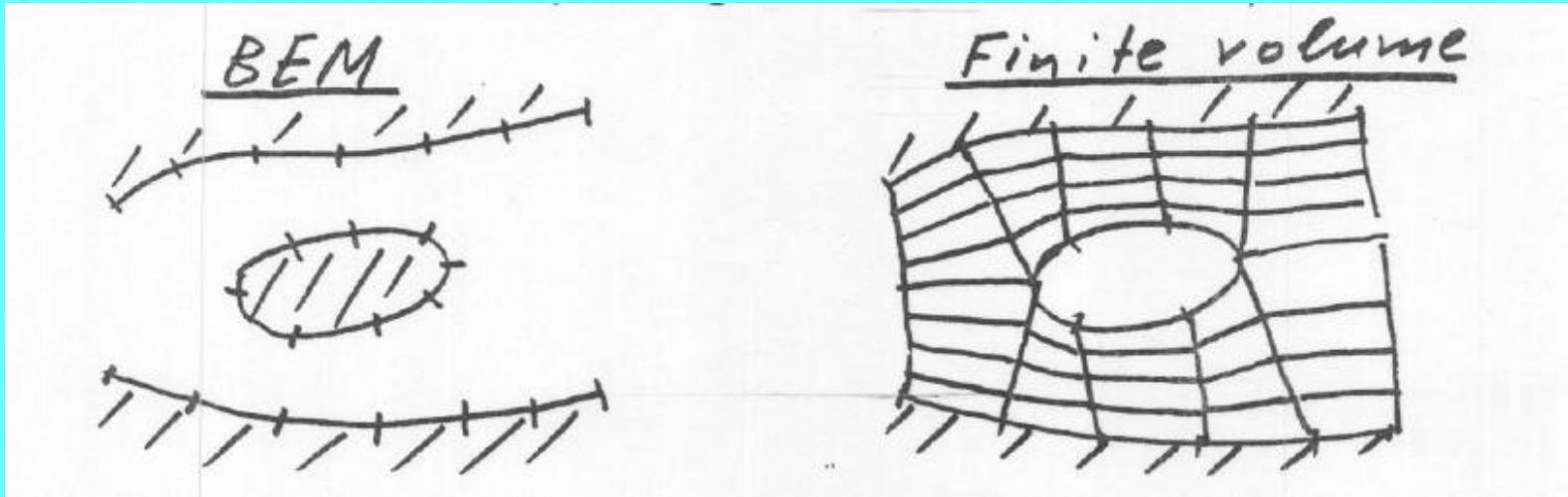
Rotating components interacting with stationary ones (propeller) (rudder)



Two methods to model flow

Boundary Element (or Panel) Method
(addressed in **CE380P.4**)

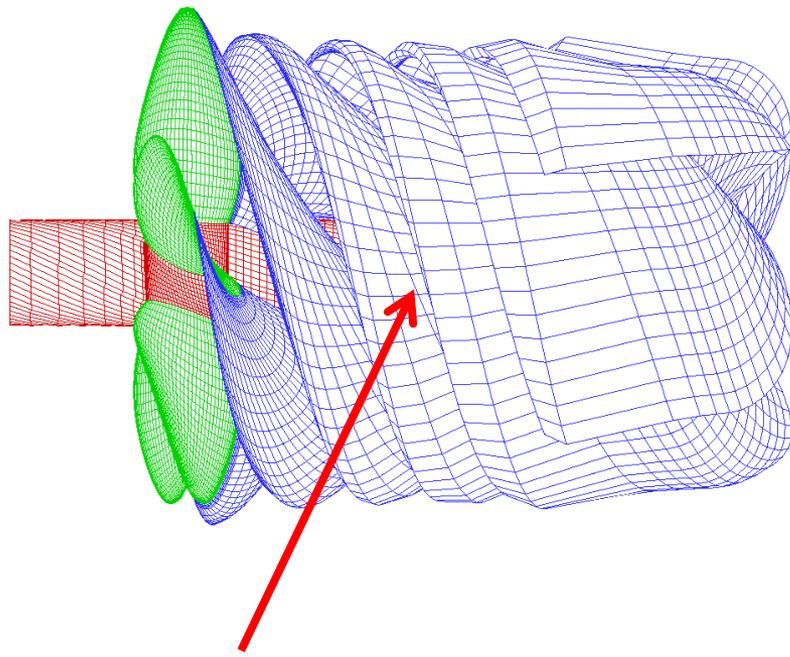
Finite Volume Method
(addressed in **CE380T**)



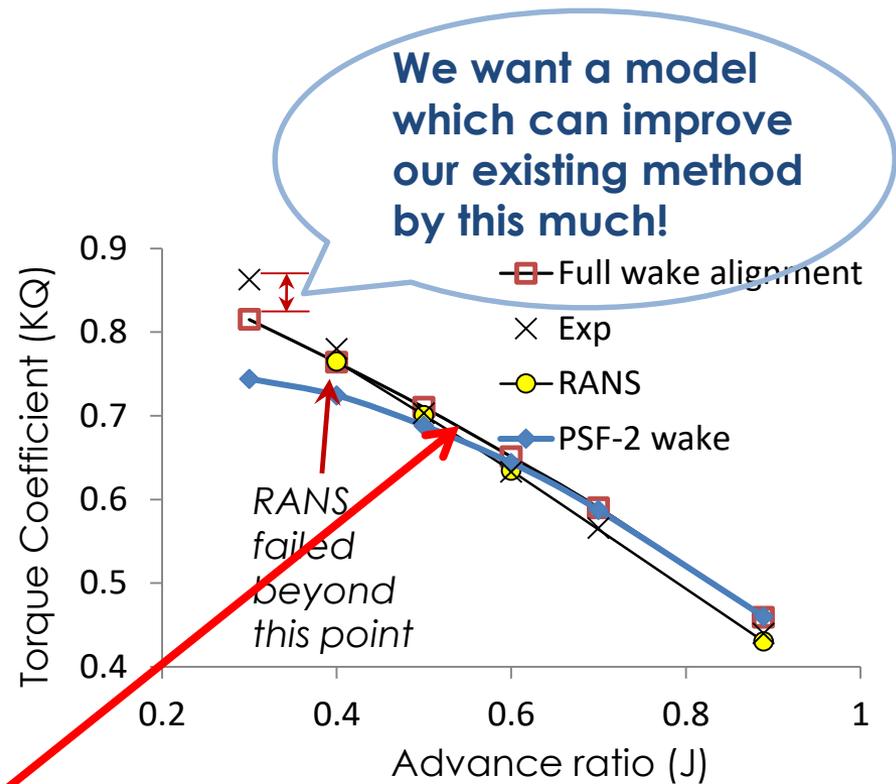
- **BEM** can only handle the inviscid part of the flow (i.e. NOT very close to boundaries). The effects of viscosity are included via coupling with integral boundary layer methods
- **FVM** needs a very large number of cells to resolve the whole domain (especially the boundary layer) within acceptable accuracy



PREDICTION OF PROPELLER PERFORMANCE AT HIGH LOADING (TIAN & KINNAS, INT. JOURNAL OF ROTATING MACHINERY, 2012)

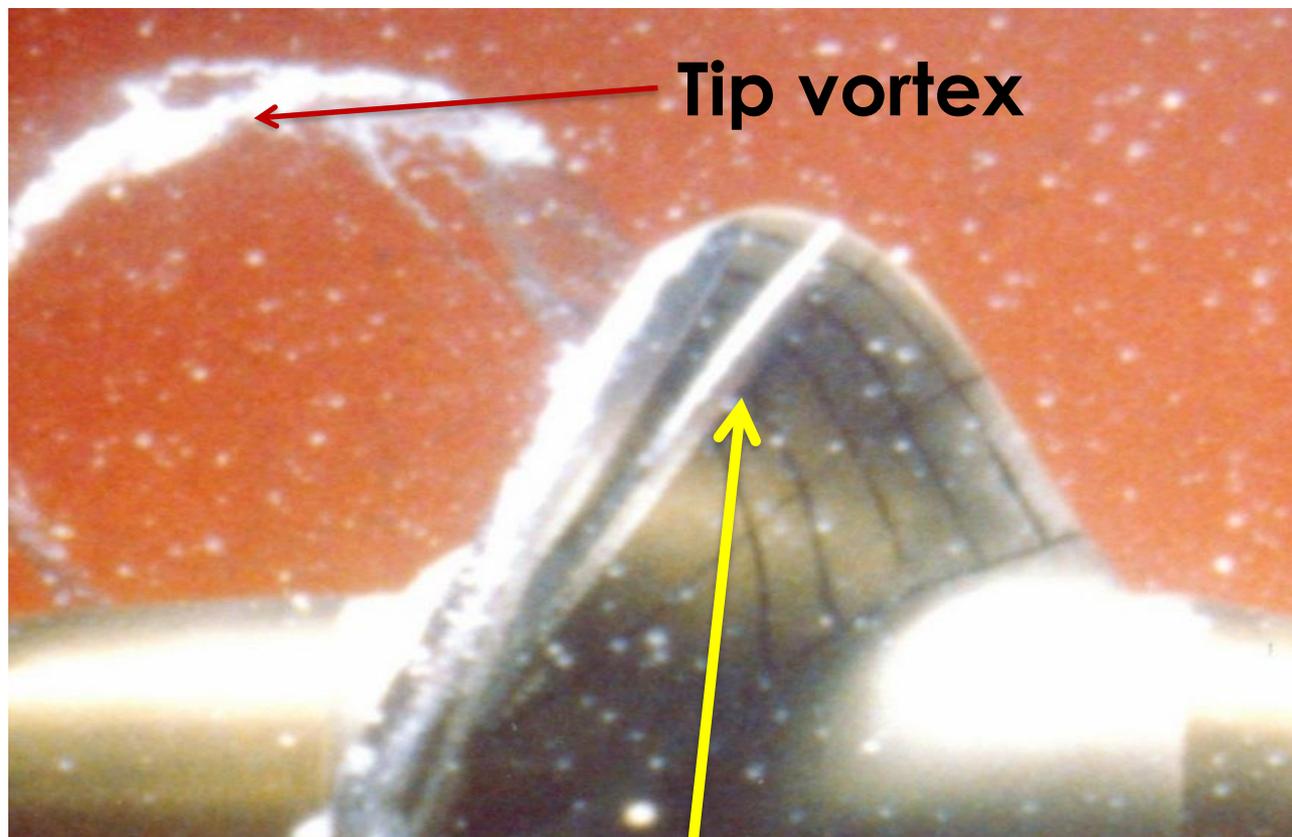


Correct position of "force-free" trailing wake improves prediction of performance



Panel method : 5 mins on a Laptop
RANS: 8 hrs on 24 CPUs.

A VISCOUS VORTICITY EQUATION (VISVE) MODEL FOR PROPELLER AT OFF-DESIGN WITH LEADING EDGE VORTEX (LEV)



Tip vortex

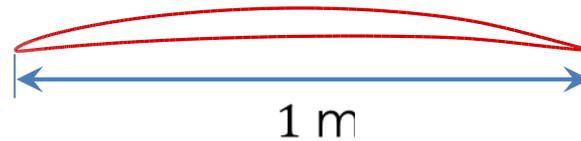
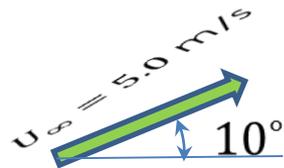
Tian, PhD
OEG/UT 2014

Tian & Kinnas;
SMP'15

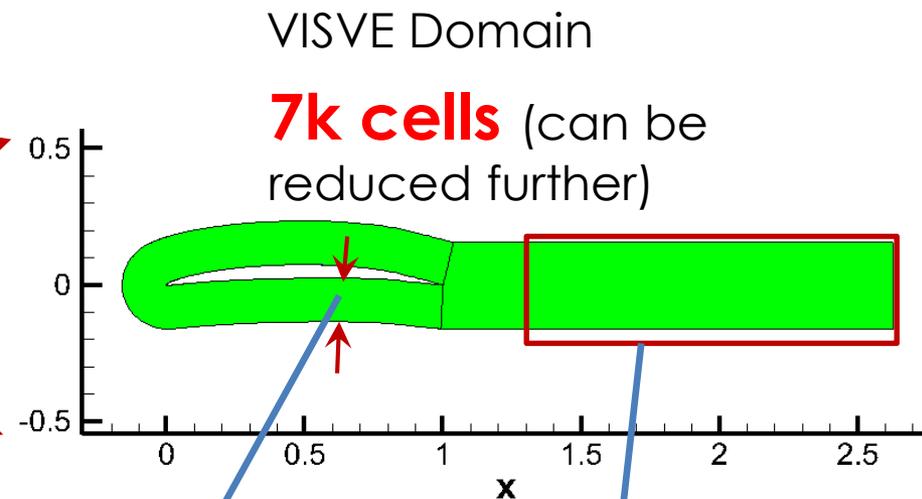
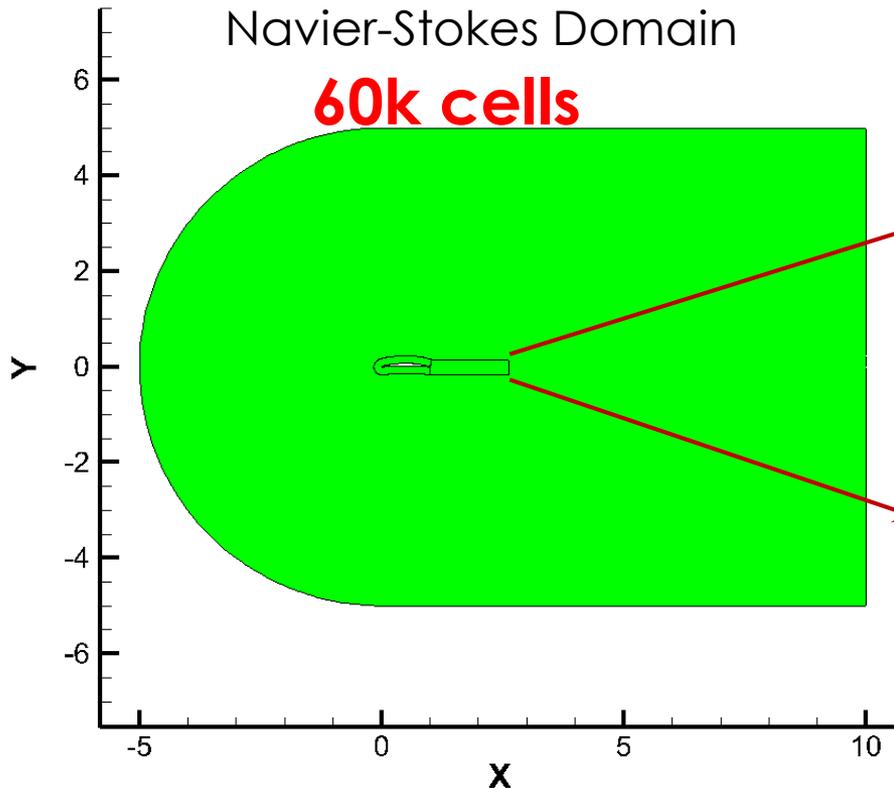
Leading edge vortex (LEV)

NEW METHOD FOR EVALUATION OF LE SEPARATION

◆ 2D hydrofoil at high angle of attack



$$Re = 5 \times 10^4$$



of layers of cells can also be reduced.

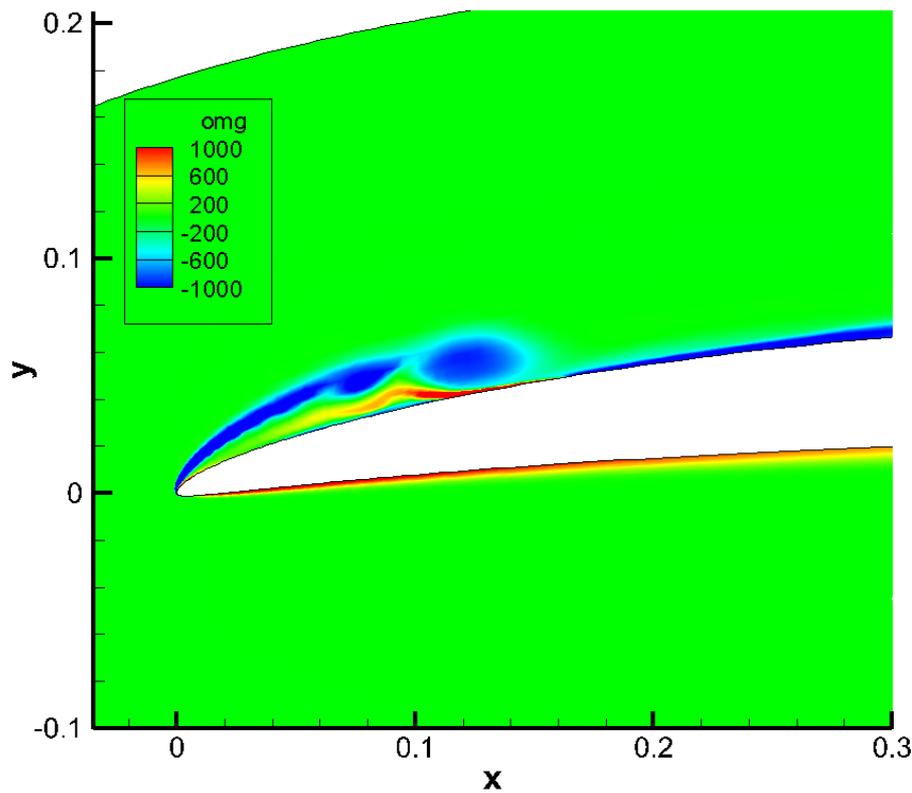
This region is NOT necessary and will be replaced.

RESULTS

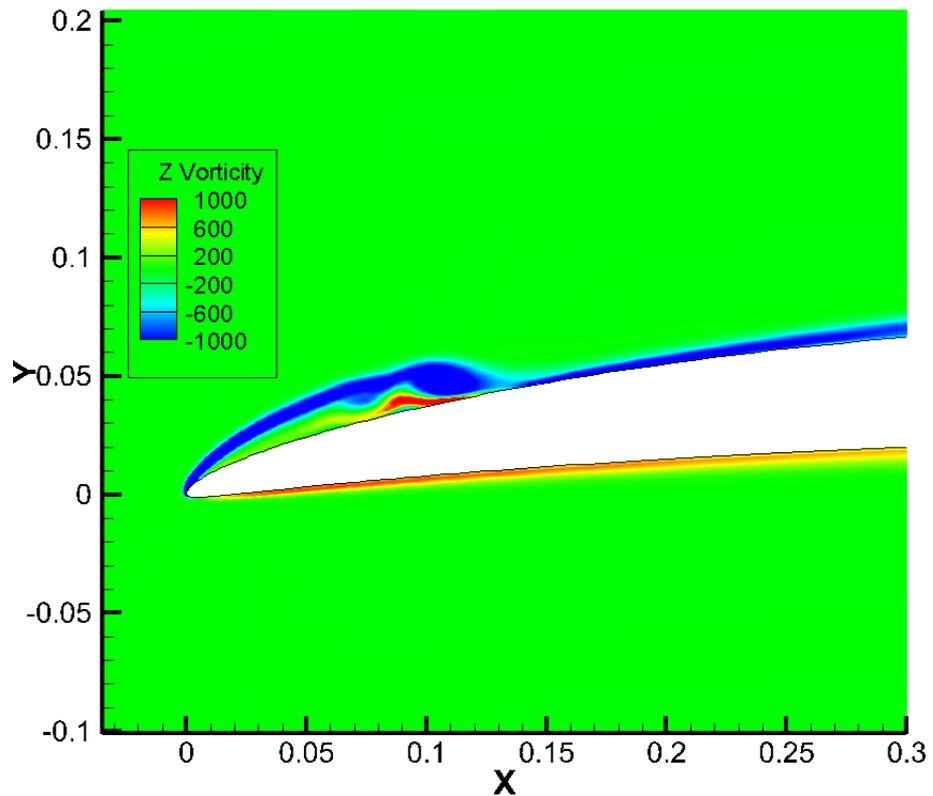
◆ 2D hydrofoil at high angle of attack

$t=0.3s$

VISVE

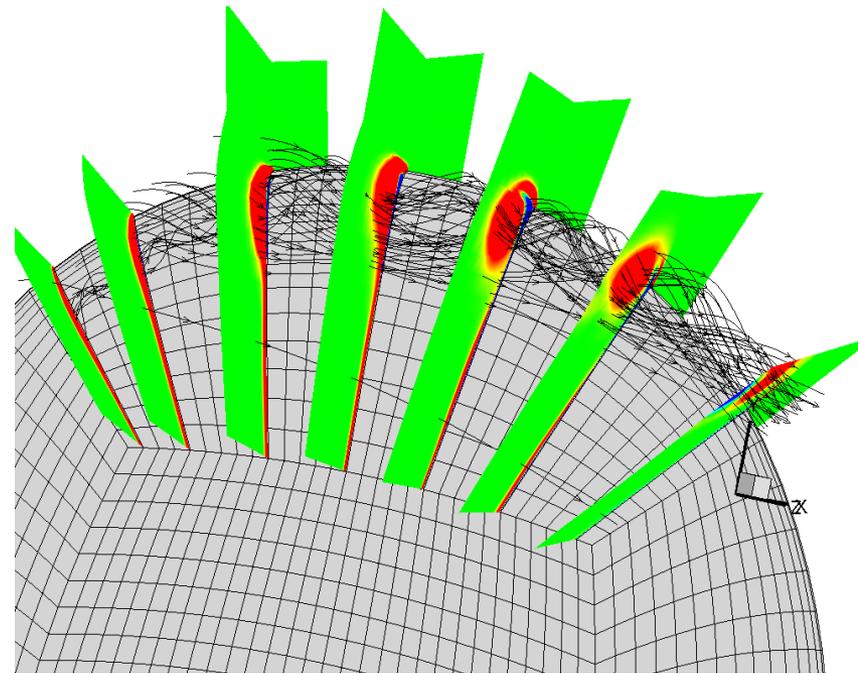
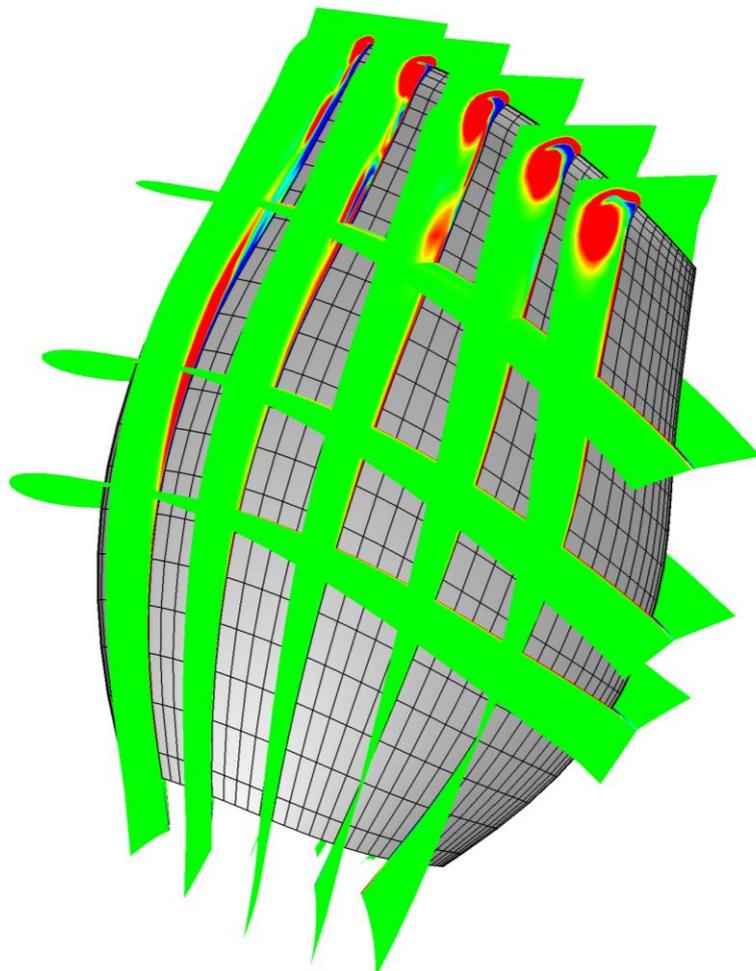


Navier-Stokes (RANS)



RESULTS (VORTICITY STRENGTH IS SHOWN IN COLOR)

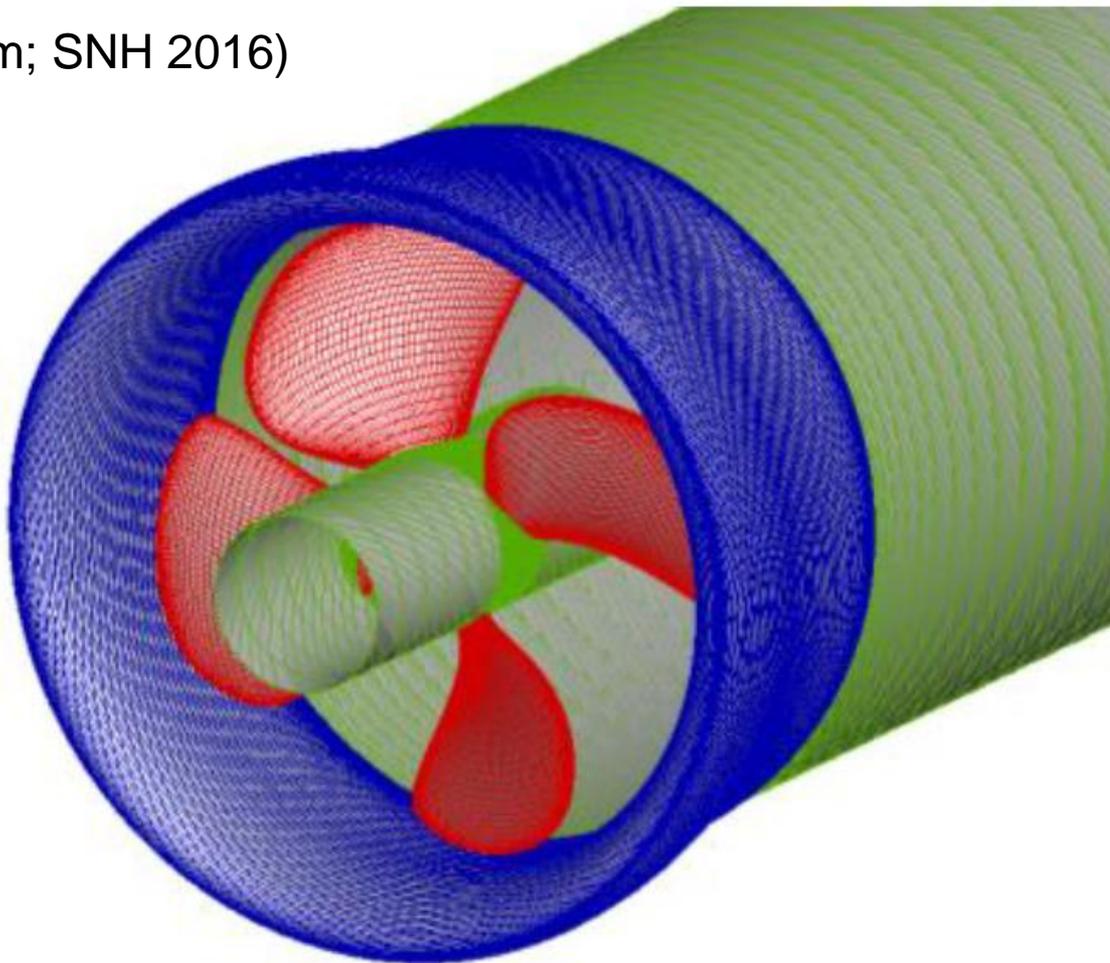
A Square Tip Propeller (left) and a Round Tip Propeller (right)





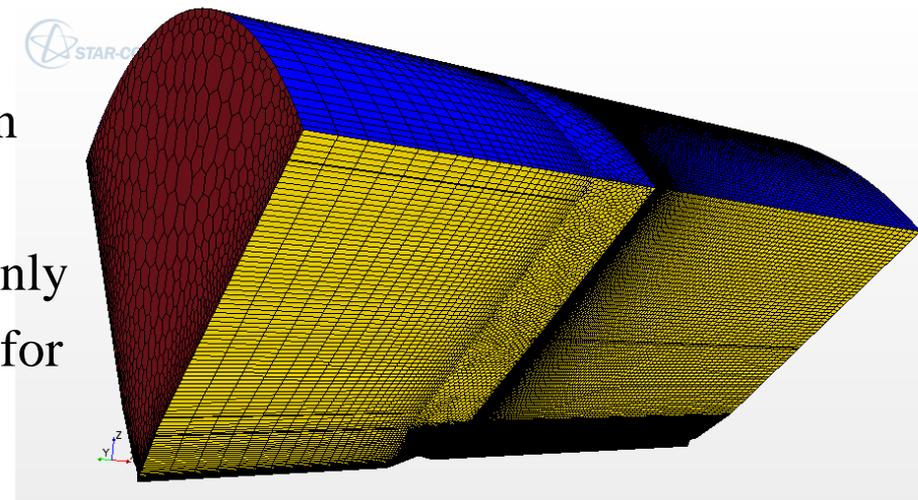
APPLICATION ON DUCTED PROPELLERS CORRELATION OF OUR METHODS WITH RANS SOLVERS (STAR-CCM+ & FLUENT)

(Kinnas, Su, Du, Kim; SNH 2016)

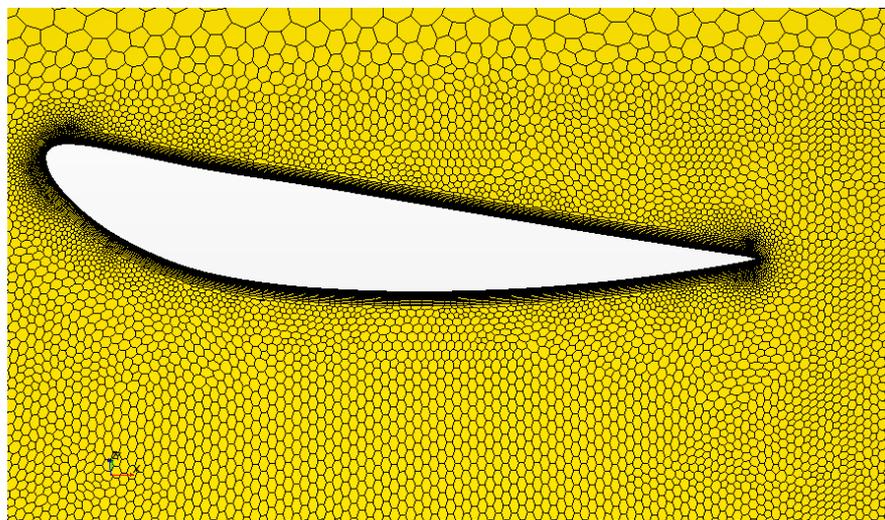


➤ Mesh conditions in fully 3-D viscous simulation

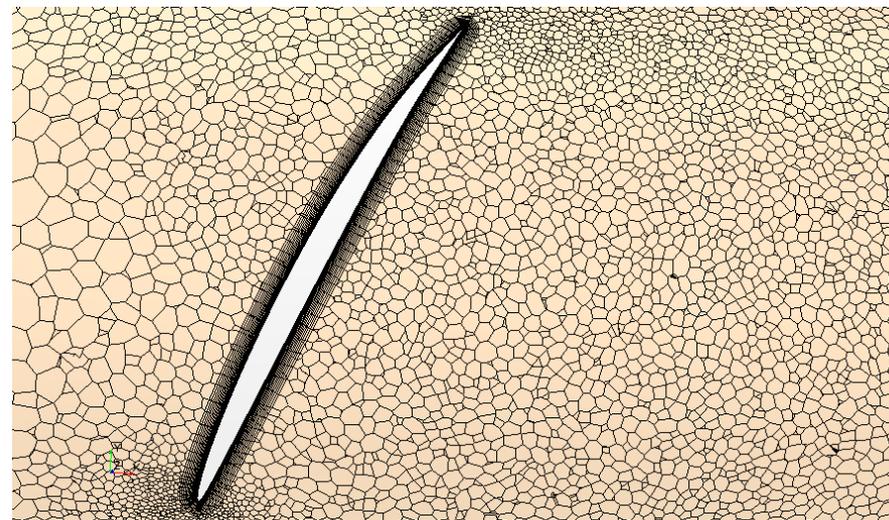
- ◆ Polyhedral cells and hexahedral cells are respectively utilized in the rotating region and static region.
- ◆ Periodic interfaces are applied, making only a quarter of the whole domain necessary for the simulation.



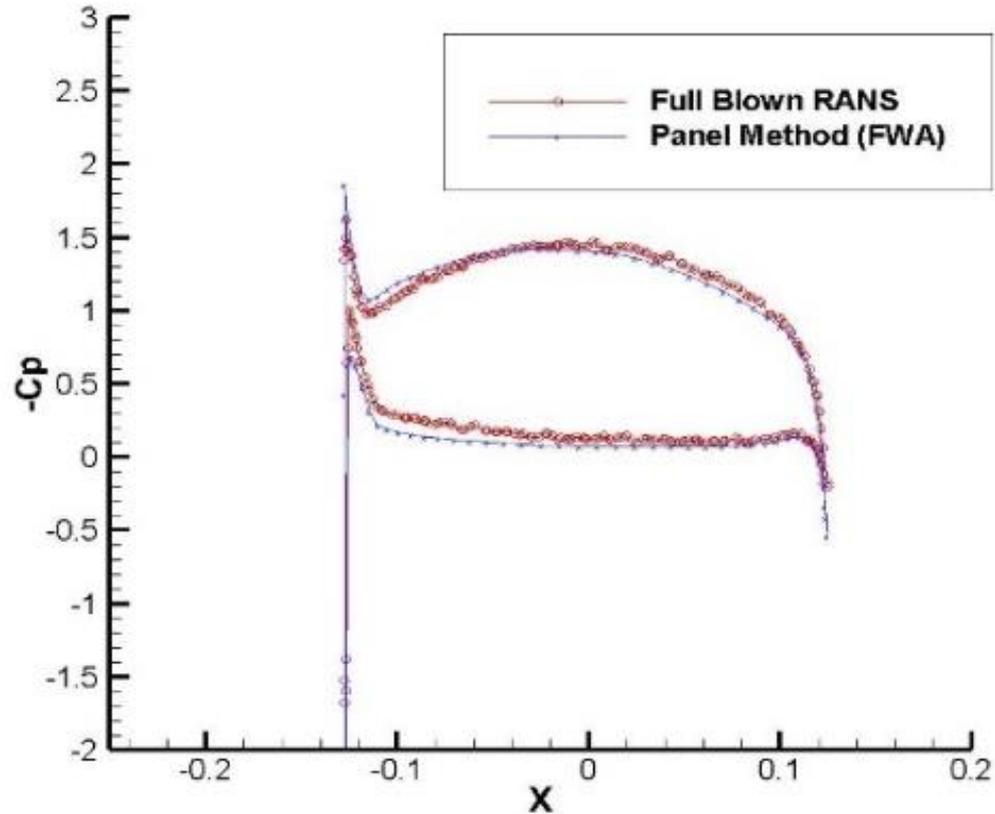
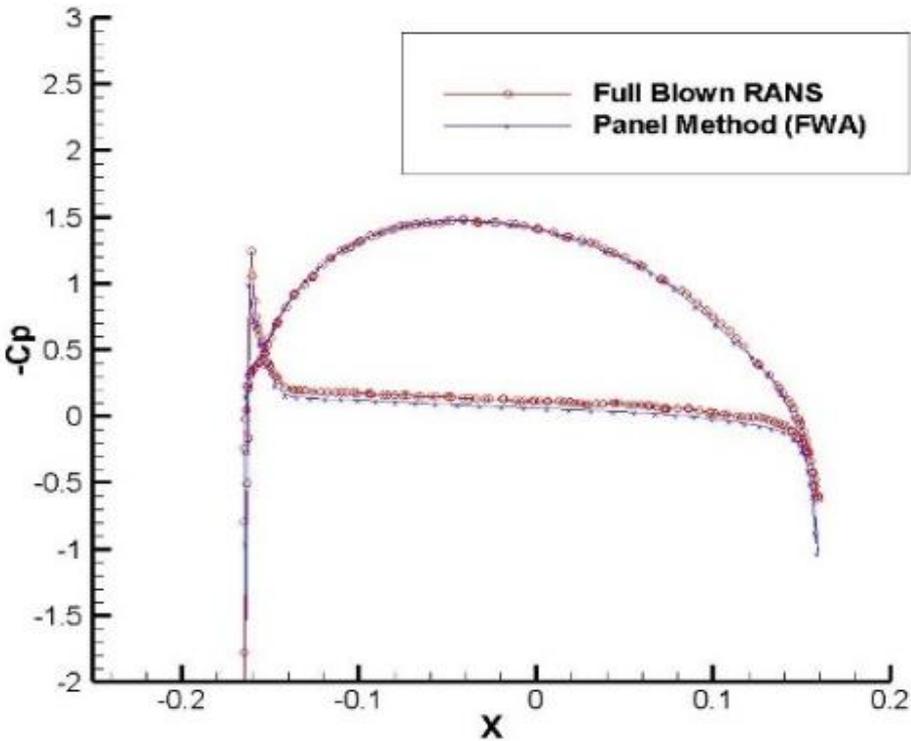
mesh of periodic domain



mesh around duct



mesh around blade station $r/R=0.60$



Correlation of pressure distribution ($J_s=0.5$) at different radial sections $r/R=0.5927$ (left), and $r/R=0.9305$ (right)



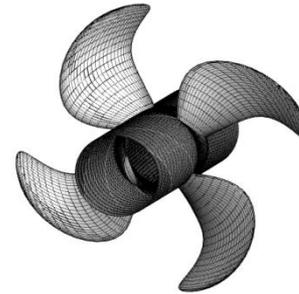
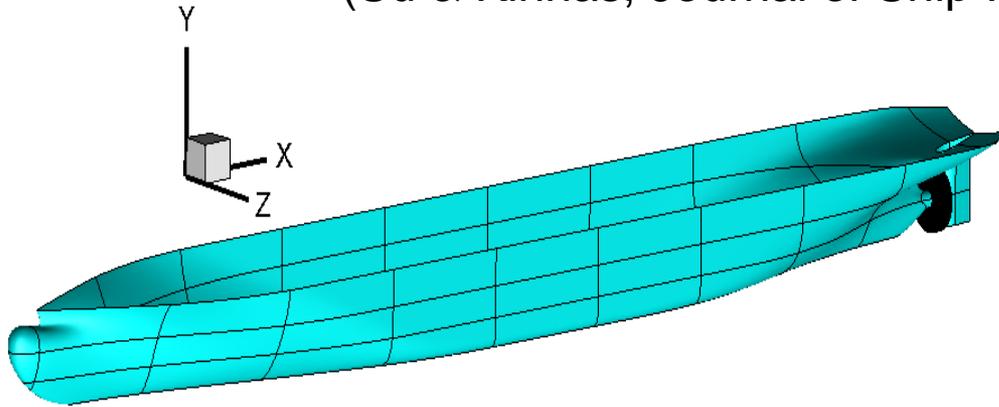
➤ Comparison of running times

Method	Full blown RANS	PANEL METHOD
Cell No.	Over 5 million cells	Less than 12K panels (10 iterations for wake)
Total running time	Over 30 hours (32 CPUs)	30 minutes (1 CPU)

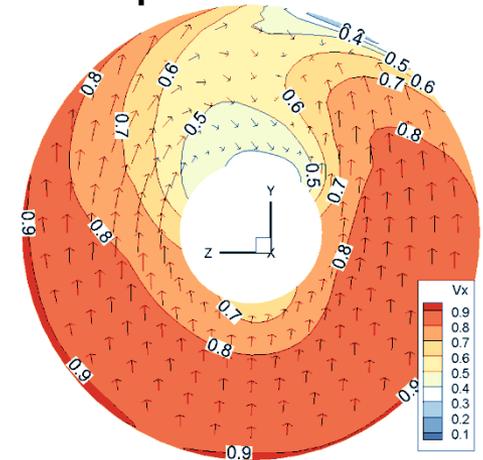
Table 4-2 Computation efficiency comparison between the panel method and the full blow RANS simulation

Ship Hull – Propeller – Rudder Interaction

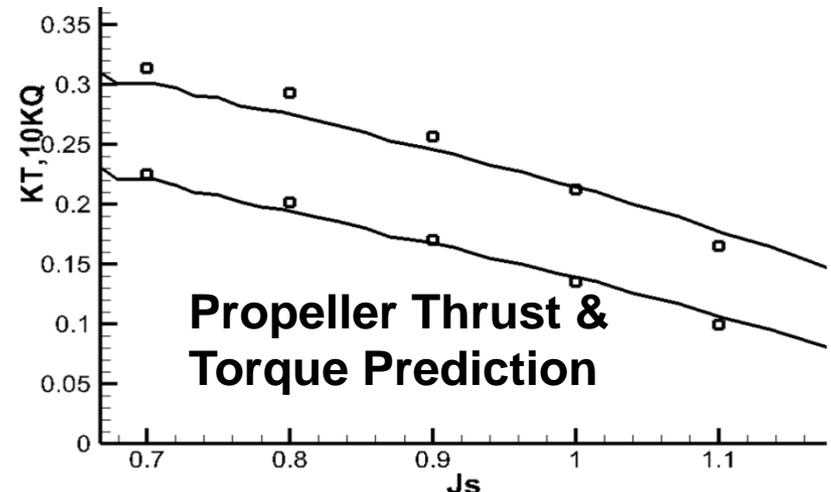
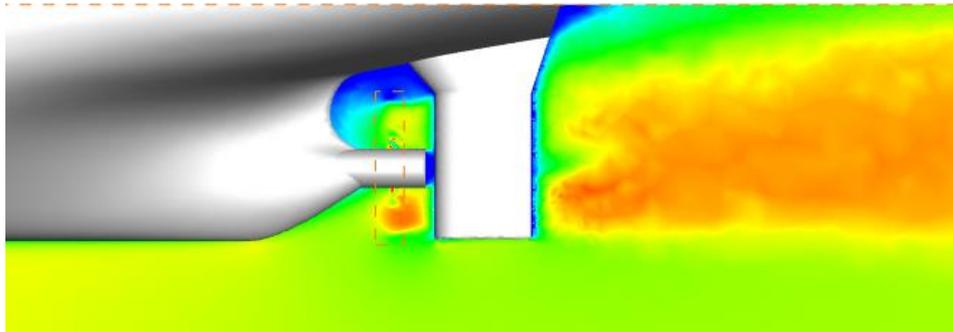
(Su & Kinnas, Journal of Ship Research, 2017 – in press)



Propeller Inflow

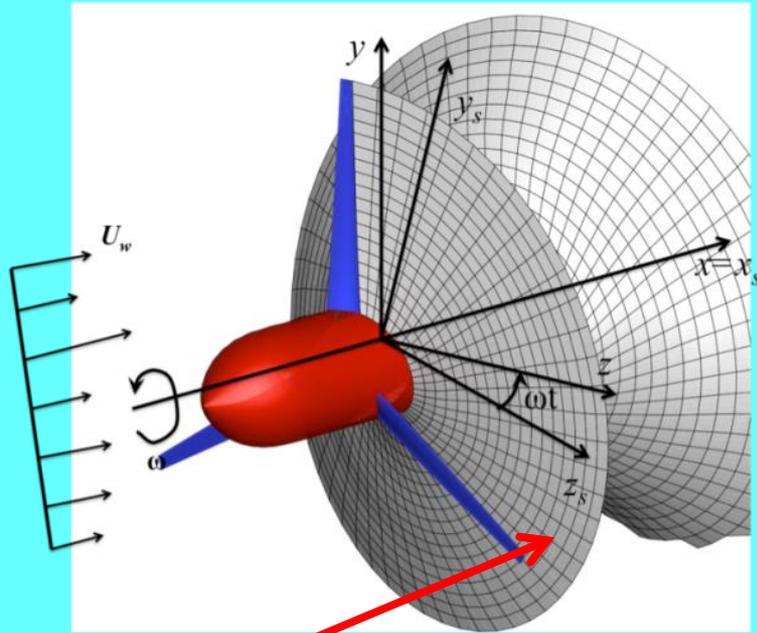


Axial Velocity/Ship Speed

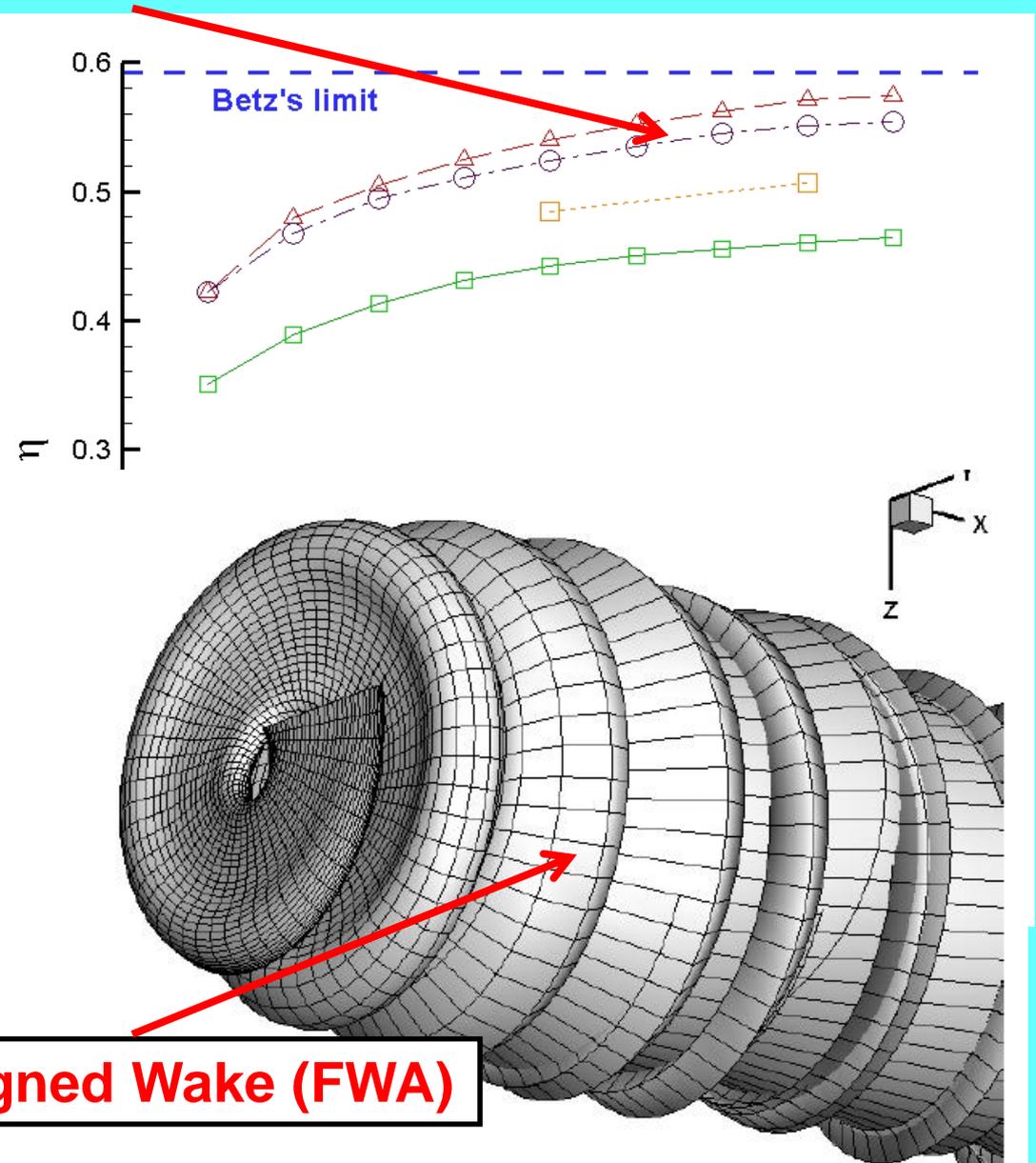


□ VLM/RANS (unsteady) mean $KT/10KQ$ — Experiment

New design method produces more efficient turbines (Menendez, MS, OEG 13, Menendez & Kinnas JSR'14)



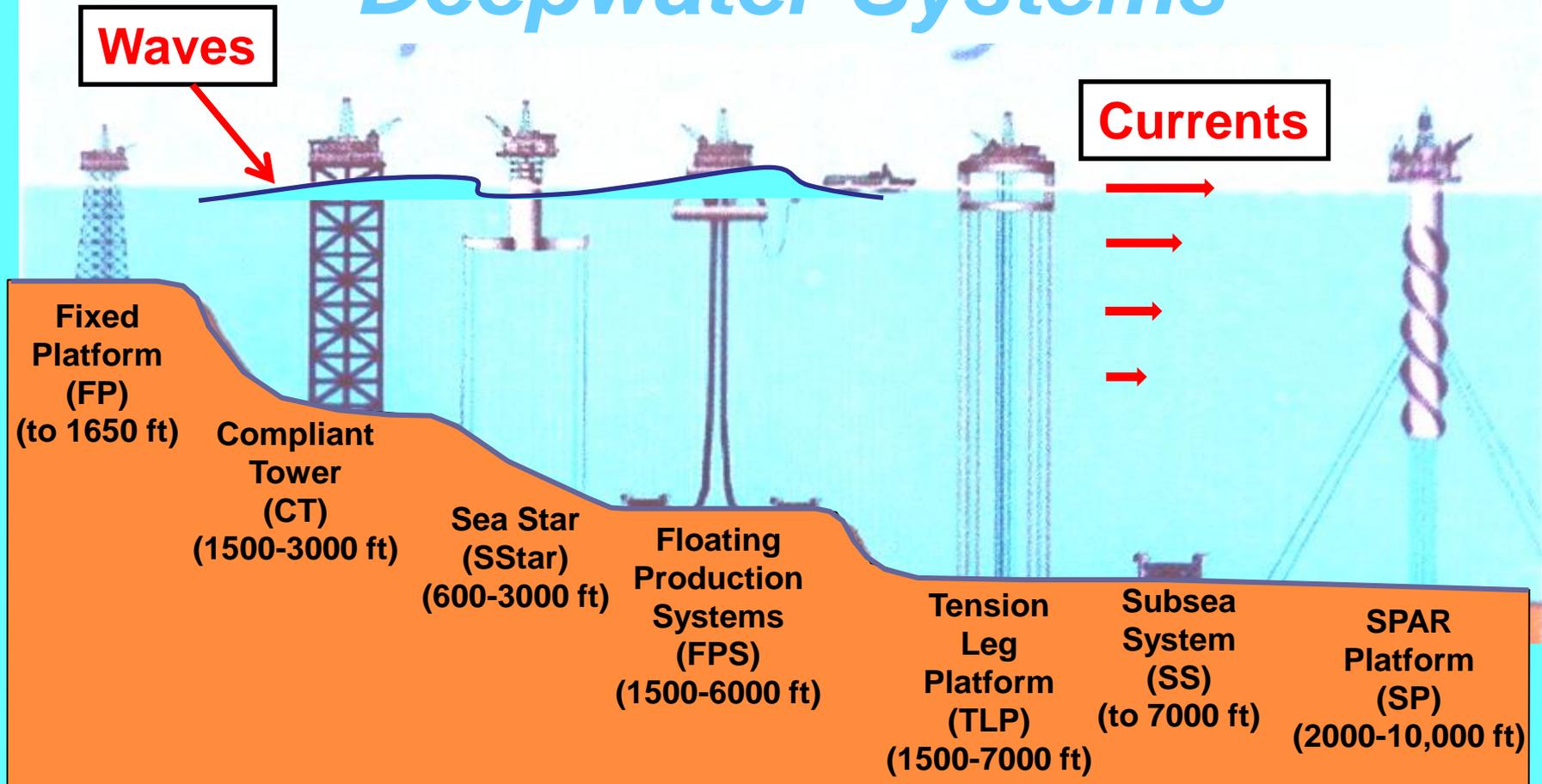
Non- or partially aligned wake



Fully Aligned Wake (FWA)

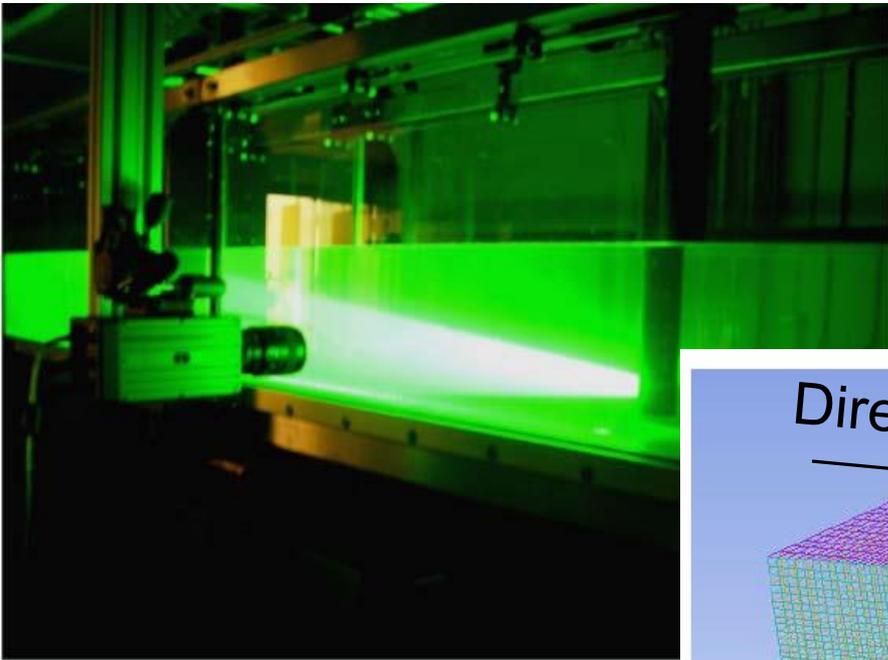
OFFSHORE PLATFORMS

Deepwater Systems



Experiment and simulation of flow around cylinder subject to wave (G. Wang; MS, OEG, 2015)

UT's flume and Particle Image Velocimetry (PIV) system



Simulation of viscous flow inside flume (using ANSYS/Fluent)

- Reynolds-Averaged Navier-Stokes (RANS)
- Large Eddy Simulation (LES)

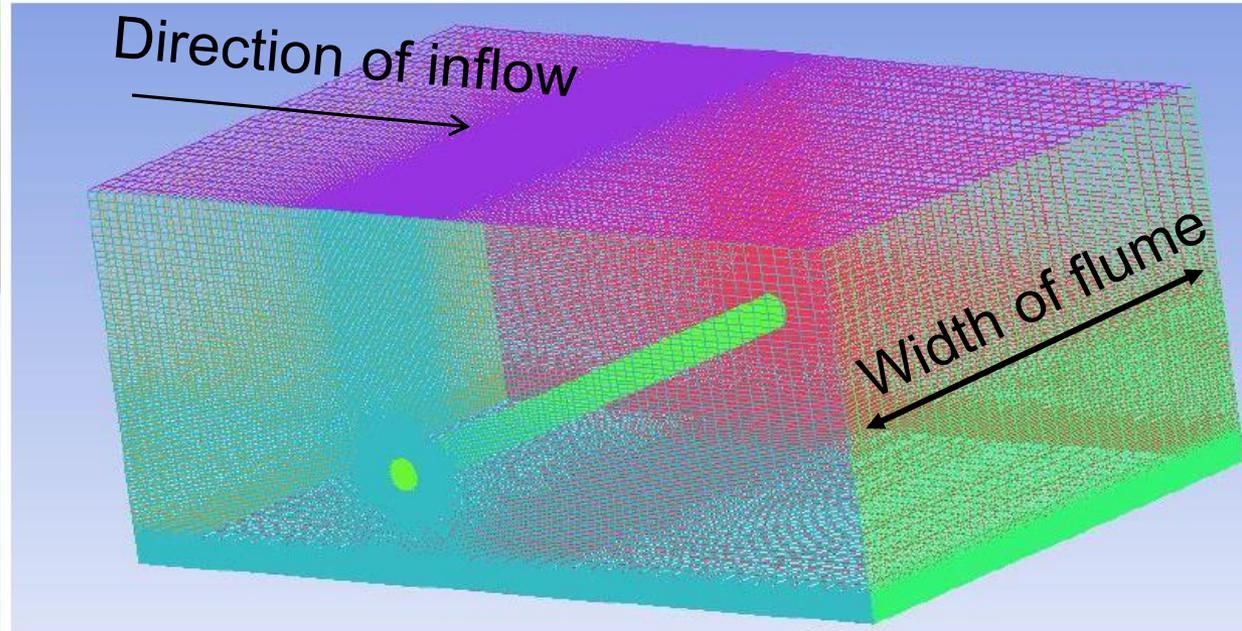


Figure 4.37 3D mesh including free surface

Measured vs. predicted velocity over time

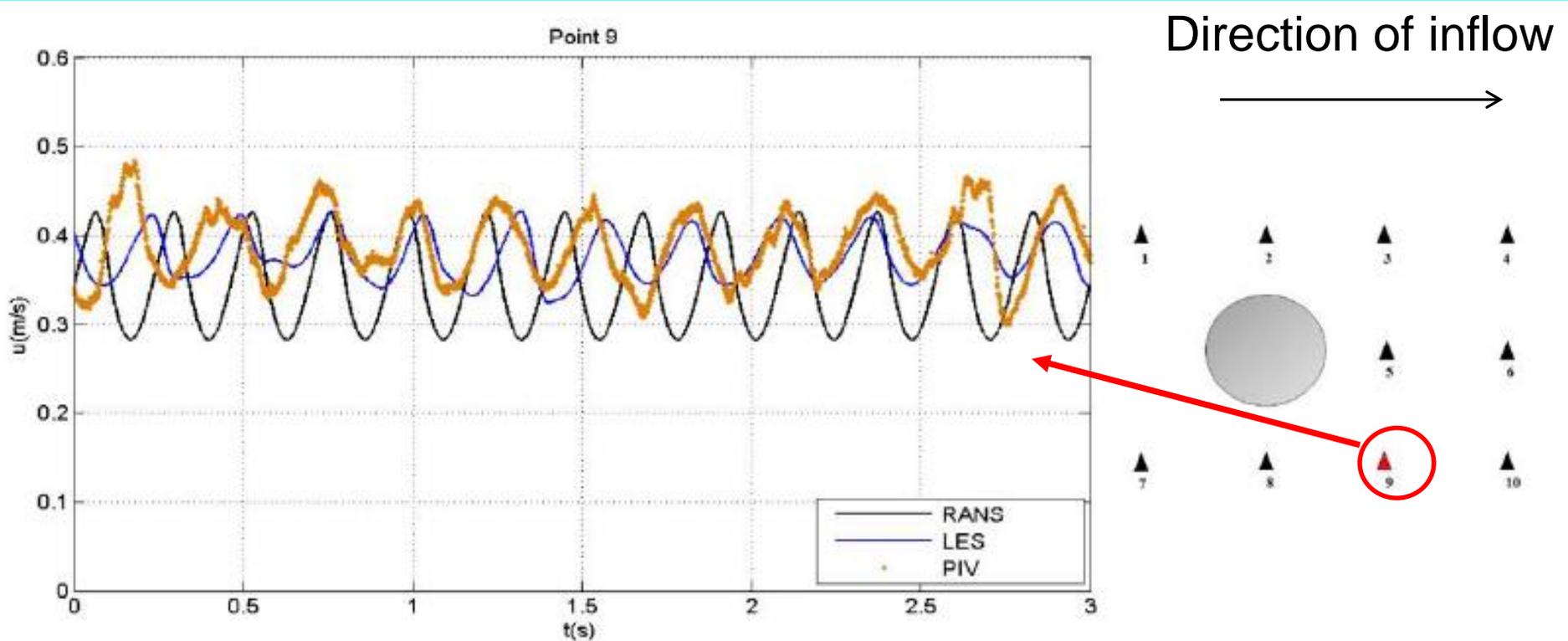


Figure 4.13 Time history of horizontal velocity of point 9

Measured vs. computed time averaged velocities (Reynolds stresses)

LES appears to do a much better job than RANS in simulating the viscous flow

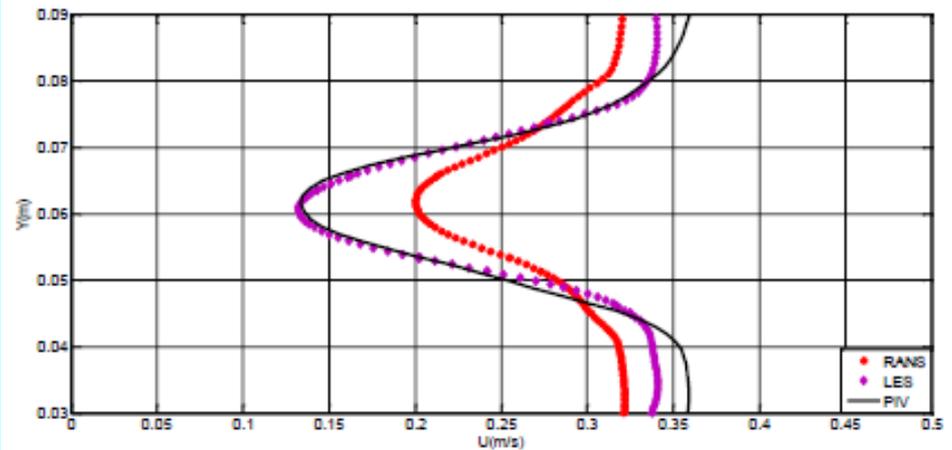


Figure 4.16 Time-averaged horizontal velocity at section 1

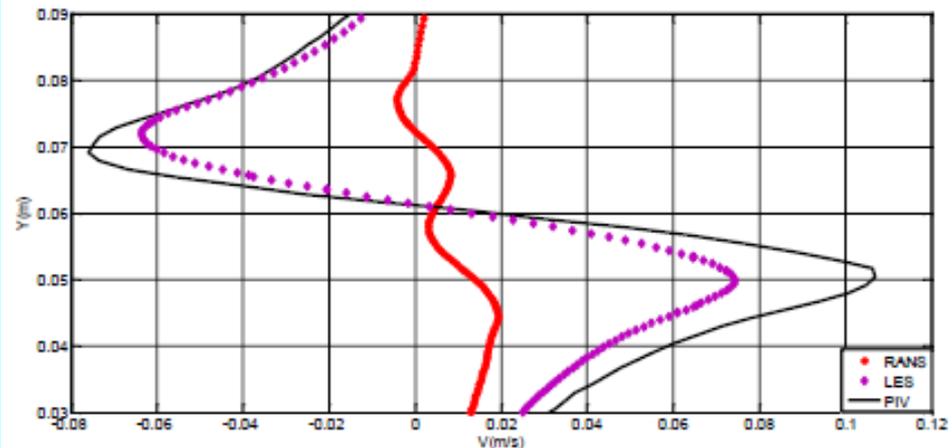


Figure 4.17 Time-averaged vertical velocity at section 1

2017-18 Opportunities in OEG:

- **10 hour grader (for CE358 class - committed)**
- **MS Thesis in OE on the topics listed (unfunded) – Requires strong background in Fluid Mechanics, Advanced Calculus, and Computational Methods**