

1 **A Bivariate Multinomial Probit Model for Trip Scheduling: Bayesian Analysis of**
2 **the Work Tour**

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34
35 **ABSTRACT**

36
37 As tour-based methods for activity and travel participation patterns replaces trip-based methods, time-
38 of-day (TOD) choice modeling remains problematic. In practice, most travel demand model systems
39 handle tour scheduling via joint-choice multinomial logit (MNL) models, which suffer from the well-
40 known independence of irrelevant alternatives (IIA) assumption. This paper introduces a random utility
41 maximization (RUM) model of tour scheduling called the bivariate multinomial probit (BVMNP). This
42 specification enables correlations across TOD alternatives, both outbound and return (on a tour) and
43 over time slots (in a day). The model is estimated in a Bayesian setting on work-tour data from the San
44 Francisco Bay Area (with 28 time slots). Empirical results suggest that a variety of individual, household,
45 and tour characteristics have reasonable effects on scheduling behavior. For instance, older persons
46 typically pursue work tours at earlier times of day, part-time workers pursue their work tours later, and
47 those with additional activities and tours tend to arrive slightly later and leave much earlier than those

48 undertaking only a single tour, everything else constant. The model out-performs a comparable MNL,
49 while offering reasonable implications under a variety of road-tolling scenarios.

50
51

52 **1. INTRODUCTION**

53

54 Activity scheduling is a key determinant of temporal variations in travel demand patterns. Yet this
55 dimension of behavior is often greatly simplified in model specifications, particularly as compared to
56 other choice dimensions, such as mode and destination (as noted in Vovsha et al. [2005] and TRB
57 [2007]). As transportation policies become more focused on congestion and demand management (see,
58 e.g., AASHTO 2007), behavioral variations across times of day are increasingly important. This is
59 particularly the case when examining variable-pricing policies (Schofer 2005), which can shift travelers'
60 time-of-day (TOD) choices to off-peak and shoulder periods.

61

62 Existing TOD models can be categorized into two broad groups: continuous and discrete. Continuous
63 models generally rely on hazard-based specifications (see, e.g., Wang 1996 and Bhat and Steed 2002,
64 among others) and allow for all times of day. As Bhat and Steed (2002) point out, discrete-choice
65 methods rely on interval boundaries, usually set rather arbitrarily, and discretization always results in a
66 loss in temporal resolution. Nonetheless, such methods typically are based in random utility
67 maximization (RUM) theory, which provides a defensible and econometrically rigorous connection to
68 microeconomic theories of behavior. Current travel demand model systems rely heavily on RUM for
69 other travel choices (such as destination and mode), often integrating such choices in a behaviorally
70 consistent fashion (via logsums, for example [see, e.g., PB Consult 2005]). Moreover, utility models offer
71 a basis for calculating consumer surplus change (see, e.g., de Jong et al. 2007 or Kockelman and Lemp
72 2009), which is useful for policy and project evaluation (including, for example, environmental justice
73 concerns). In addition, existing continuous methods do not appear capable of consistently incorporating
74 the two-plus timing features of a tour (with possible exception of the continuous cross-nested logit
75 model [Lemp et al. 2010]).

76

77 Most of the earliest TOD models used discrete choice methods. For example, in the context of work trip
78 timing, Abkowitz (1981) and Small (1982) used the multinomial logit (MNL), while Chin (1990) turned to
79 the nested logit and Small (1987) developed the ordered generalized extreme value (OGEV) model (to
80 alleviate the independence of irrelevant alternatives (IIA) assumption). In each case, however, the
81 choice spectrum was limited to the AM peak period, rather than the entire day. For large-scale demand
82 systems, temporal variations across the entire day are needed.

83

84 Several researchers have modeled TOD choice for the entire day (with MNL and OGEV model
85 specifications), using broad alternative intervals of 3 or more hours (see, e.g., Bhat 1998 and Steed and
86 Bhat 2000). Recent advances in activity-based modeling (where the unit of travel is the tour, rather than
87 the trip) have led to the application of several two-dimensional TOD choice models (since a tour has at
88 least two timing components: outbound and return legs). Vovsha and Bradley (2004), Abou Zeid et al.
89 (2006), and Popuri et al. (2008) modeled tour timing in this way, using joint MNL specifications, each
90 with relatively short (30-minute or 1-hour) alternatives.

91

92 While discrete choice methods offer several advantages over continuous methods, most applications of
93 two-dimensional TOD choice models in large-scale travel demand model systems use MNL specifications
94 (see, e.g., PB Consult 2005). This is partly because it offers closed-form choice-probability expressions,
95 but also because it can be estimated with relative ease, even with large numbers of alternatives. When

96 relatively short TOD choice intervals are considered (e.g., 1 hour or 30 minutes), the number of joint
97 choice alternatives grows quickly in two dimensions. However, one would expect error term
98 correlations to exist between alternatives close in time, and the MNL cannot accommodate such
99 correlations.

100
101 To address the various issues described above, this paper describes a type of two-way autoregressive
102 error term correlation structure for a multinomial probit (MNP) model of tour TOD choices. The model
103 is estimated on work tour data from the 2000 San Francisco Bay Area Travel Survey (BATS). To
104 accommodate the open-form probability expressions of the MNP, Bayesian estimation techniques are
105 employed. And, to avoid the large number of alternatives that emerge with short time intervals (of 30
106 minutes, as used here) across two timing dimensions, a bivariate MNP (BVMNP) specification is used,
107 where each commuter chooses exactly two (rather than one) alternatives, one from each timing
108 dimension.

109
110 The next section specifies the BVMNP model, while Section 3 discusses the Bayesian estimation
111 procedures used. Section 4 introduces the data set, Section 5 presents analytical results, and Section 6
112 offers some concluding remarks.

113

114 **2. BIVARIATE MULTINOMIAL PROBIT FORMULATION**

115

116 Like the MNL, the multinomial probit (MNP) relies on a latent random utility specification. However, the
117 random error terms follow a normal distribution (rather than a type I extreme value, or Gumbel,
118 distribution). The normality results in open-form expressions for alternative probabilities (unlike the
119 MNL), which is why the MNP has not been utilized to a greater extent in the literature. Thanks to
120 Bayesian and other sophisticated statistical methods, one need not assume error terms are independent
121 and identically distributed with the MNP. In this section, a bivariate MNP (BVMNP) model specification
122 for tour TOD choice is formulated, where the twin variables of interest are a tour's home-to-work arrival
123 time and work-to-home departure time.

124

125 **2.1 Random Utility Framework and Model Specification**

126

127 Each alternative in an MNP model has a (latent) random utility, and the decision-maker always chooses
128 the alternative offering the greatest underlying utility value. Since the MNP model developed here
129 seeks to reflect two-dimensional travel-timing, the choice context needs special attention. One
130 reasonable way to approach the problem is to consider it in a single dimension. Instead of choosing tour
131 arrival times and tour return times, one may assume that individuals jointly choose tour arrival and
132 return times, and the analyst need only consider a single choice dimension. For instance, consider the
133 following joint utility specification:

134

$$135 \quad U(t_a, t_r) = V_1(t_a) + V_2(t_r) + V_3(t_r - t_a) + \varepsilon_{ar} \quad (1)$$

136

137 Here, V_1 is the systematic utility component related to arrival time t_a , V_2 is the component related to
138 return time t_r , and V_3 is the component related to duration $t_r - t_a$. A key difficulty with this approach
139 is that one is usually interested in rather small time intervals as alternatives; and, in two dimensions, the
140 number of alternatives can become quite large. For instance, if 30-minute intervals are used, one has
141 1,176 alternatives. For an MNP model, this produces a covariance matrix of size 1,176 x 1,176,
142 presenting a number of computational difficulties in model estimation. With this in mind, a bivariate
143 multinomial probit (BVMNP) model is developed here, where tour arrival time represents one choice

144 dimension and tour return time represents another. While the BVMNP model has been used in previous
 145 studies (see, e.g., Golob and Regan 2002 and Zhang et al. 2008), no previous work has investigated
 146 choice contexts with more than three or four alternatives. In addition, the estimation procedure used
 147 here varies from traditional methods, in order to accommodate the large number of alternatives. In this
 148 bivariate context, one must specify two separate utility functions (one for tour arrival and another for
 149 tour return), as follows:

$$150 \quad U_{aj} = V_{aj} + \varepsilon_{aj} \quad (2)$$

$$151 \quad U_{rl} = V_{rl} + \varepsilon_{rl} \quad (3)$$

152
 153 Here, U_{aj} and U_{rl} denote latent utilities for arrival and return time alternatives j and l , V_{aj} and V_{rl} are
 154 systematic utility components, and ε_{aj} and ε_{rl} are random error components. The set of arrival time
 155 alternatives is identical to the set of return time alternatives, with arrival time alternatives indexed by
 156 $j = 1, \dots, J$ and return time alternatives indexed by $k = 1, \dots, J$. While this specification does not allow
 157 for a utility component specifically related to tour/activity duration, it does significantly reduce the
 158 number of choice alternatives. For instance, if time-of-day is modeled in 30-minute intervals over the
 159 24-hour day period (as it is here), this results in 96 alternatives (and utility values), rather than the 1,176
 160 needed for the joint choice model.
 161

162 2.2 Error Correlation Structure

163 Since one cannot reasonably assume independence of alternatives, the correlation structure of the error
 164 components deserves some attention. While it is theoretically feasible to estimate the entire covariance
 165 matrix without imposing any pre-specified structure, there is a clear ordering of alternatives, which
 166 evokes certain expectations for covariance properties. With this in mind, a specific structure is imposed
 167 here.
 168

169 One can imagine a variety of correlation structures. Here, a pseudo-AR specification of covariance
 170 components is pursued. Components of the covariance matrix are formulated directly, with the upper
 171 left and lower right quadrants taking on forms *similar to* a typical AR1 process (though it is worth noting
 172 that the formulation cannot be directly interpreted as an AR1 process). Off-diagonal quadrants are
 173 formulated slightly different, due to bivariate interactions between work arrival and return times,
 174 though covariance components appear similar to those of an AR1 process. The covariance matrix is
 175 specified as follows:
 176
 177

$$178 \quad \Sigma = \begin{bmatrix} \mathcal{W}_a & \mathcal{C} \\ \mathcal{C}' & \mathcal{W}_r \end{bmatrix} \quad (4)$$

$$179 \quad \mathcal{W}_a = \begin{bmatrix} w_{a11} & \dots & w_{a1J} \\ \vdots & \ddots & \vdots \\ w_{aJ1} & \dots & w_{aJJ} \end{bmatrix}, w_{apq} = \lambda_a^{|t_p - t_q|} \sigma_a^2 \quad (5)$$

$$180 \quad \mathcal{W}_r = \begin{bmatrix} w_{r11} & \dots & w_{r1J} \\ \vdots & \ddots & \vdots \\ w_{rJ1} & \dots & w_{rJJ} \end{bmatrix}, w_{rpq} = \lambda_r^{|t_p - t_q|} \sigma_r^2 \quad (6)$$

$$181 \quad \mathcal{C} = \begin{bmatrix} c_{11} & \dots & c_{1J} \\ \vdots & \ddots & \vdots \\ c_{J1} & \dots & c_{JJ} \end{bmatrix}, c_{pq} = \begin{cases} 0 & \text{for } p > q \\ \sigma_a \sigma_r \lambda_d^{|(t_q - t_p) - (\mu_1 + \mu_2 t_p)| + 1} & \text{for } p \leq q \end{cases} \quad (7)$$

182
 183

184 Here, \mathcal{W}_a and \mathcal{W}_r are covariance matrices defining the error structure within the arrival time dimension
185 and within the return time dimension, and \mathcal{C} and \mathcal{C}' are the covariance matrices defining the error
186 structure across arrival and return times. Arrival time- and return time-specific variances are denoted
187 by σ_a^2 and σ_r^2 , respectively, λ_a and λ_r are correlation coefficients of arrival and return utility
188 components separated by 1 hour, and $\lambda_d^{|(t_q-t_p)-(\mu_1+\mu_2t_p)|+1}$ is the correlation coefficient between
189 arrival and return utility components. One last item needing attention here is the role of μ_1 and μ_2
190 (which define the “baseline” duration on which elements of \mathcal{C} are based). Essentially, the model posits
191 that some activity duration may be highly desired (e.g., 8 hours for full-time workers arriving at work
192 around 9 am), and this term allows correlations across arrival and return time utilities to be highest for
193 such durations. The “baseline” duration is equal to some constant, μ_1 , plus an additional term that
194 varies over the work arrival time, μ_2t_p . Of course, it is not reasonable to view μ_1 and μ_2 as two fixed
195 values, since one expects differences across individuals or classes of individuals. This is particularly
196 important since work duration is not reflected in the systematic utility equations. Here, μ_1 and μ_2 are
197 taken to be two separate parameters each, two for full-time workers making no additional tours during
198 the day ($\mu_{1,\text{full}}$ and $\mu_{2,\text{full}}$) and two for part-time workers and/or those making additional tours ($\mu_{1,\text{part}}$
199 and $\mu_{2,\text{part}}$), adding a layer of observed heterogeneity to the model.¹ Of course, one may expect
200 preferred durations to vary with other traveler attributes, and one could control for those too. The
201 reason μ_1 and μ_2 are differentiated here only between full-time workers (with no additional tours) and
202 part-time workers (and/or those making additional tours) is that this distinction seems most important.
203 If μ_1 and μ_2 differed for each individual, Σ would also differ for each individual, requiring computation of
204 distinct Σ 's for each observation, which can be computationally expensive. By allowing μ_1 and μ_2 to vary
205 over only two traveler groups, the estimation process is streamlined, with only two covariance matrices,
206 Σ_{full} and Σ_{part} , thus facilitating demonstration of the model here.

207
208 In this paper, 30-minute time intervals serve as the choice alternatives. Since there are very few
209 individuals choosing times very early in the day and very late in the day (for both arrival and return
210 choice dimensions), boundary alternatives were needed, essentially grouping many 30-minute
211 alternatives into a single alternative. Since these boundary intervals may exhibit very different
212 properties than non-boundary alternatives, their variances and correlations adjusted, as described
213 below.

214
215 First, each of the four boundary alternatives' error terms is allowed to have its own variance parameter,
216 denoted by σ_{a1}^2 , σ_{aJ}^2 , σ_{r1}^2 , and σ_{rJ}^2 . Second, correlation coefficients between utility components are
217 assumed to be inversely related to each alternative's interval size. More specifically, these parameters
218 are assumed to vary across each pair of alternatives as follows:

$$220 \quad \text{Corr}(p_a, q_a) = \lambda_a^{|t_{p_a}-t_{q_a}|} \left(\frac{\text{size}_p}{\text{size}_{\text{def}}}\right)^{-\tau_{ar}} \left(\frac{\text{size}_q}{\text{size}_{\text{def}}}\right)^{-\tau_{ar}} \quad (8)$$

$$221 \quad \text{Corr}(p_r, q_r) = \lambda_r^{|t_{p_r}-t_{q_r}|} \left(\frac{\text{size}_p}{\text{size}_{\text{def}}}\right)^{-\tau_{ar}} \left(\frac{\text{size}_q}{\text{size}_{\text{def}}}\right)^{-\tau_{ar}} \quad (9)$$

$$222 \quad \text{Corr}(p_a, q_r) = \lambda_d^{|t_{q_r}-t_{p_a}-(\mu_1+\mu_2t_{p_a})+1|} \left(\frac{\text{size}_p}{\text{size}_{\text{def}}}\right)^{-\tau_d} \left(\frac{\text{size}_q}{\text{size}_{\text{def}}}\right)^{-\tau_d} \quad (10)$$

223

¹ The distinction here was chosen because average travel durations for full-time workers in the data sample were found to be about 8.2 hours, while average travel durations for both part-time workers and those making additional tours during the day were found to be about 6 hours.

224 Here, $size_{def}$ is 30 minutes (the default interval size), and $size_p$ and $size_q$ are the interval sizes of
 225 alternatives p and q (measured in minutes). λ_a , λ_r , and λ_d are the same as described above, and τ_{ar}
 226 and τ_d are two new (non-negative) parameters to be estimated. The assumption of non-negativity
 227 presumes that correlations between boundary alternatives and other alternatives are smaller than those
 228 across non-boundary alternatives. It should be clear that the size terms only come into play when one
 229 or both of the alternatives are boundary alternatives. Moreover, these size terms reduce to the original
 230 model specification if τ_{ar} or τ_d is zero. Finally, it is worth noting that τ_{ar} affects both the correlations
 231 across arrival alternatives and those across departure alternatives. Thus, it is assumed that the way in
 232 which the interval size affects correlation patterns across arrival times is the same as the way it affects
 233 correlation patterns across return times.

234

235 2.3 Systematic Utility Construction

236

237 Finally, the systematic utility specifications for arrival time and return time utilities take the forms shown
 238 in equations 3.2 and 3.3. Since each alternative represents a discrete time interval, the t in the utility
 239 equation is taken to be the midpoint of the time interval. For notational convenience, the systematic
 240 utilities for arrival time and return time alternatives are rewritten as follows:

241

$$242 \quad V_{i,aj} = X_{ij}\beta_a + \sum_{p=1}^P \eta_{ap}g_{i,ap}(t_j) \quad (11)$$

$$243 \quad V_{i,rl} = X_{il}\beta_r + \sum_{p=1}^P \eta_{rp}g_{i,rp}(t_l) \quad (12)$$

244

245 Here, $g_{i,ap}(t_j)$ and $g_{i,rp}(t_l)$ represent network characteristics of type p (such as travel time and
 246 reliability) for arrival and return time intervals t_j and t_l ; and β_a , β_r , η_a , and η_r are parameters to be
 247 estimated. Similar to MNL and other choice models, covariates that do not vary over time alternatives
 248 (e.g., an individual's gender or age) cannot be introduced in the normal way. One can imagine any
 249 number of continuous forms to use in this context. Here, X_{ij} and X_{il} represent row vectors of
 250 individual-specific attributes interacted with cyclical functions (like the utility formulations of Abou Zeid
 251 et al. 2006 and Popuri et al. 2008). That is, X_{ij} and X_{il} have the following forms:

252

$$253 \quad X_{ij} = \begin{bmatrix} X_{i1}\sin(2\pi t_j/24) \\ X_{i1}\sin(4\pi t_j/24) \\ \vdots \\ X_{i1}\sin(2Q_1\pi t_j/24) \\ X_{i1}\cos(2\pi t_j/24) \\ \vdots \\ X_{i1}\cos(2Q_1\pi t_j/24) \\ X_{i2}\sin(2\pi t_j/24) \\ \vdots \\ X_{i2}\cos(2Q_2\pi t_j/24) \\ \vdots \\ X_{iK}\sin(2\pi t_j/24) \\ \vdots \\ X_{iK}\cos(2Q_K\pi t_j/24) \end{bmatrix}', \quad X_{il} = \begin{bmatrix} X_{i1}\sin(2\pi t_l/24) \\ X_{i1}\sin(4\pi t_l/24) \\ \vdots \\ X_{i1}\sin(2Q_1\pi t_l/24) \\ X_{i1}\cos(2\pi t_l/24) \\ \vdots \\ X_{i1}\cos(2Q_1\pi t_l/24) \\ X_{i2}\sin(2\pi t_l/24) \\ \vdots \\ X_{i2}\cos(2Q_2\pi t_l/24) \\ \vdots \\ X_{iK}\sin(2\pi t_l/24) \\ \vdots \\ X_{iK}\cos(2Q_K\pi t_l/24) \end{bmatrix}'$$

254

$$x_i = \begin{bmatrix} x_{i1} & 0 & g_{i,a}(t_1) & 0 \\ \vdots & 0 & \vdots & 0 \\ x_{ij} & 0 & g_{i,a}(t_j) & 0 \\ 0 & x_{i1} & 0 & g_{i,r}(t_1) \\ 0 & \vdots & 0 & \vdots \\ 0 & x_{ij} & 0 & g_{i,r}(t_j) \end{bmatrix}$$

255

$$\begin{bmatrix} V_{i,a} \\ V_{i,r} \end{bmatrix} = x_i \begin{bmatrix} \beta_a \\ \beta_r \\ \eta_a \\ \eta_r \end{bmatrix} \quad (13)$$

257

258

259 The number of individual-specific attributes is K , with each individual attribute interacted with $2Q_k$
 260 cyclical functions (Q_k for sine functions and Q_k for cosine functions). Some covariates may be interacted
 261 with fewer than $2Q_k$ cyclical functions by restricting the applicable elements of β_a and β_r to be zero.
 262 There are a couple of reasons for selecting this utility form. First, it allows utility to take on a rich
 263 assortment of shapes, including multimodal ones. In addition (and as pointed out by Abou Zeid et al.
 264 2006 and Popuri et al. 2008), 24 hours is a multiple of each cyclical function's period, which offers day-
 265 to-day consistency in the utility function (e.g., utilities at 0 and 24 hours are identical). And by
 266 construction, the systematic utilities are linear in unknown parameters.

267

268 3. BVMNP PARAMETER ESTIMATION

269

270 Estimation of the BVMNP model can be performed via MCMC simulation. Bayesian techniques are
 271 particularly well-suited for estimation of the BVMNP (or any MNP for that matter) since classical
 272 methods generally rely on simulated maximum likelihood estimation (MSLE) to avoid numerical
 273 evaluation of multi-dimensional integrals involved in the likelihood (McFadden 1989 and Geweke et al.
 274 1994).

275

276 In the standard Bayesian construction of the MNP model (see, e.g., Albert and Chib 1993, McCulloch and
 277 Rossi 1994, and Zhang et al. 2008, among others), one need not evaluate choice probabilities at all. For
 278 the MNP model, the dependent variable, Y_i , can take on values 1, 2, ..., J , where Y_i 's value simply
 279 indexes the chosen alternative. With the latent random utility specification of the model, the
 280 probability of Y_i taking on a value q is given by the following:

281

$$P(Y_i = q) = P(U_{iq} \geq \max_{p \in J} U_{ip}) \quad (14)$$

282

283 In other words, the choice probability of alternative q is equivalent to the probability that the latent
 284 utility associated with alternative q is the maximum utility value. Here, U_i is treated as a random
 285 (nuisance) parameter to be estimated and is normally distributed (under the MNP model specification),
 286 with mean given by the systematic utility, V_i , and variance given by Σ . For the BVMNP model, Y_i is
 287 simply taken to be bivariate, with joint choice probability of arrival time q_1 and return time q_2 given by
 288 the following:

289

$$P(Y_i = [q_1, q_2]) = P(U_{i,aq_1} \geq \max_{p \in J} U_{i,ap} \cap U_{i,rq_2} \geq \max_{p \in J} U_{i,rp}) \quad (15)$$

290

291

292

293 The joint choice probability of arrival time q_1 and return time q_2 is equivalent to the probability that the
294 latent utility associated with arrival time alternative q_1 is the maximum utility across all arrival time
295 alternatives and that the latent utility associated with return time alternative q_2 is the maximum utility
296 across all return time alternatives. Bayesian estimation proceeds via a three-step Gibbs sampler as
297 follows:

- 298
299 Step 1: Draw $U_i | V_i, \Sigma_i, X_i, Y_i \forall i$
300 Step 2: Draw $\lambda, \mu, \sigma, \tau | U_i, V_i, X_i, Y_i \forall i$
301 Step 3: Draw $\beta_a, \beta_r, \eta | U_i, \Sigma_i, X_i, Y_i \forall i$
302

303 The Gibbs sampler does not generate draws for σ_a^2 or σ_r^2 (the variances of non-boundary alternatives)
304 here. It is well known that the MNP requires one element of Σ to be fixed for identification purposes
305 (see, e.g., McCulloch and Rossi 1994). However, with the BVMNP, one element of Σ must be fixed for
306 each nominal measure (Zhang et al. 2008). Thus, σ_a^2 or σ_r^2 are fixed at 1 for identification purposes,
307 though boundary alternative variances are estimated.

308
309 In step 1, a normal random walk Metropolis-Hastings (MH) step (see, e.g., Gamerman and Lopes 2006) is
310 used to draw an individual's utility values simultaneously. The proposal density for the MH step is a
311 multivariate normal, with mean equal to the current utility values, and covariance given by $\kappa \Sigma_i$. Here,
312 Σ_i is the utility covariance matrix for individual i , computed from the current values of covariance
313 parameters, and κ is a deflation factor to increase the probability of proposal acceptance. The deflation
314 factor was set to $\kappa = 0.05$, after calibrating the parameter to achieve approximately 25% proposal
315 acceptance. It was found that this MH algorithm is much more computationally stable than the typical
316 Gibbs sampling algorithm, and it reduces computation time per iteration by nearly one half.
317 Unfortunately, since utility values are more restricted in their movements from one iteration to the
318 next, the algorithm is slow to converge.

319
320 In the second step of the Gibbs sampler, a draw of the covariance matrix parameters is generated.
321 Priors on λ_a, λ_r , and λ_d are specified to be independent uniform distributions over the interval from 0
322 to 1, reflecting a belief that there should be positive correlation across alternative utilities. Priors on
323 $\mu_{1,\text{full}}$ and $\mu_{1,\text{part}}$ are specified to be independent normal distributions with means of 9 and 6 (hours),
324 respectively, and variances of 2 each, while priors on $\mu_{2,\text{full}}$ and $\mu_{2,\text{part}}$ are specified to be normal
325 distributions, each with means and variances of 0 and 1, respectively. Independent gamma priors are
326 employed for $\sigma_{a1}^2, \sigma_{aJ}^2, \sigma_{r1}^2$, and σ_{rJ}^2 , each with shape and scale parameters of 2 and 1, respectively,
327 while τ_{ar} and τ_d are assumed to follow independent gammas with shape and scale parameters of 1
328 each in the prior. The gamma prior restricts these parameters to be positive. Thus, the full conditional
329 posterior distribution of the variance parameters can be written as follows²:

330

² When conditioned on U_i and V_i , $\lambda, \mu, \sigma_{a1}^2, \sigma_{aJ}^2, \sigma_{r1}^2, \sigma_{rJ}^2$, and τ are independent of X_i and Y_i .

331 $p(\lambda, \mu, \sigma, \tau | U_i, V_i \forall i) \propto H_1 H_2$ (16)

332 where,

333 $H_1 = |\Sigma_{\text{full}}|^{-n_{\text{full}}/2} |\Sigma_{\text{part}}|^{-n_{\text{part}}/2} \exp\left(-\frac{1}{2}(\sum_i (U_i - V_i)' \Sigma_i^{-1} (U_i - V_i))\right)$

334 $H_2 = (\sigma_{a1}^2 \sigma_{aJ}^2 \sigma_{r1}^2 \sigma_{rJ}^2) \exp\left(-\frac{1}{2}\left(\sum_{q=1}^4 \frac{(\mu_q - \bar{\mu}_q)^2}{\sigma_q^2}\right) - (\sigma_{a1}^2 + \sigma_{aJ}^2 + \sigma_{r1}^2 + \sigma_{rJ}^2 + \tau_{ar} + \tau_d)\right)$

335 $\sum_{q=1}^4 \frac{(\mu_q - \bar{\mu}_q)^2}{\sigma_q^2} = \frac{(\mu_{1,\text{full}} - 9)^2}{4} + \frac{(\mu_{1,\text{part}} - 6)^2}{4} + (\mu_{2,\text{full}})^2 + (\mu_{2,\text{part}})^2$

336

337 Since the density here is not in any standard form (with respect to the parameters), a MH step is used to
 338 draw these parameters. The proposal density is assumed to be normal, with mean given by the current
 339 draw of the parameters (i.e., a normal random walk) and variance initially taken to be very small and
 340 updated during the estimation process to aid in generating good proposals (see, e.g., Holden et al.
 341 2009).

342

343 In the last step of the Gibbs sampler, a draw of β_a, β_r , and η is generated from the full conditional
 344 posterior distribution. For notational convenience, write $\beta = [\beta_a', \beta_r', \eta']'$. Here, the prior for these
 345 parameters is chosen to be multivariate normal with mean $\bar{\beta}$ and covariance matrix Σ_β . Thus, the full
 346 conditional posterior is proportional to the following³:

347

348 $p(\beta | U_i, \Sigma_i, X_i \forall i) \propto$

349 $\exp\left(-\frac{1}{2}\left((\beta - \bar{\beta})' \Sigma_\beta^{-1} (\beta - \bar{\beta}) + \sum_i (U_i - X_i \beta)' \Sigma_i^{-1} (U_i - X_i \beta)\right)\right)$ (17)

350

351 Suppose Ω and Λ are given by the following:

352

353 $\Lambda = \Sigma_\beta^{-1} \bar{\beta} + \sum_i X_i' \Sigma_i^{-1} U_i$ (18)

354 $\Omega = (\Sigma_\beta^{-1} + \sum_i X_i' \Sigma_i^{-1} X_i)^{-1}$ (19)

355

356 Expression 17 suggests that β is proportional to a multivariate normal distribution with mean given by
 357 $\Omega \Lambda$ and covariance matrix Ω . Thus, β is drawn from a multivariate normal distribution. Here, vague
 358 prior parameters are specified, with $\bar{\beta}$ taken to be a vector of zeroes, off-diagonal elements of Σ_β taken
 359 to be zeroes, and diagonal elements of Σ_β set to be very large. Since each network variable should
 360 affect utilities negatively, the normal prior distributions for η were truncated above at zero. That is all
 361 that is needed to generate the MCMC draws for this BVMNP model.

362

363 4. DATA DESCRIPTION

364

365 The data used here come from the 2000 San Francisco Bay Area Travel Survey (BATS). The survey
 366 collected travel information for roughly 17,000 households over a 2-day period. The observational unit
 367 is the travel tour (over 100,000 recorded tours), with network attributes provided for each of five TOD
 368 periods and seven modes. In addition, each record was coded with a variety of demographic and travel
 369 information. Since the analysis is focused on work-related travel, the sampling frame was restricted to
 370 the first home-based work tour made on a weekday for an individual (over the 48-hour survey period),
 371 limiting the sample to about 18,000 tours.

³ Note that conditional on $\Sigma_{\text{full}}, \Sigma_{\text{part}}, U_i$, and X_i , β is independent of Y_i .

372
373 Model estimation is very computationally burdensome due to the large number of utility values that
374 must be drawn for each individual (one for each alternative). So, an $n = 997$ random sample of tours
375 was used in model estimation.

376
377 Since time-varying network variables (as shown in equations 11 and 12) are not contained in the data
378 (though the data does contain network information across 5 broad time-of-day periods), regression
379 equations were developed to impute average travel time and its variance. A similar methodology to
380 that of Popuri et al. (2008) was used to this end. For brevity, the results of these models are not
381 presented here, though it should be noted that the models appropriately predict travel times and
382 variances to be highest during typical AM and PM peak periods. Lemp (2009) provides more details on
383 these results.

384 385 **5. EMPIRICAL RESULTS**

386
387 Given the nature of the full conditional distribution for the random utilities, the Gibbs sampler was very
388 slow to converge. It is well-known that in high-dimensional utility choice models convergence could be
389 an issue due to poor mixing; however, researchers supplement this by ensuring that the resulting
390 estimates are contextually reasonable, which is the approach we adopted. (For details, see Rossi et al.
391 2005, and the many references therein.) It is important to note that maximum likelihood estimates are
392 also difficult to obtain in these models. There is simply no guarantee of obtaining global maxima when
393 the likelihood surface is as complicated (i.e., highly multimodal) as the one in this paper.

394
395 The utility function utilizes eight individual-specific variables plus a constant. These variables include an
396 indicator for males, age of the individual, an indicator for part-time workers, an indicator for high
397 income households (over \$75,000 per year), household size, the number of tours undertaken by the
398 individual over the entire day (excluding the modeled tour), travel distance to the destination, and a
399 variable indicating whether the destination zone is coded as central business district (CBD). Table 1
400 presents the estimation results.

401

Table 1: Model Estimation Results

Variable		Arrival-Specific Utility		Return-Specific Utility	
		Mean Estimate	95% Interval	Mean Estimate	95% Interval
LOS Variables	Travel Time (min)	-0.0038	(-0.0092, -0.0037)	-0.0058	(-0.0157, -0.0053)
	Travel Time Variance (min ²)	-0.0011	(-0.0026, -0.0011)	-0.0005	(-0.0016, -0.0005)
	Cost (\$)	-0.0465	(-0.1369, -0.0342)	-0.0554	(-0.1577, -0.0467)
Constant Interactions	Sin(2*pi*t/24)	0.3822	(-0.1965, 0.4000)	-2.947	(-3.982, -2.923)
	Sin(4*pi*t/24)	-0.9215	(-1.378, -0.9134)	-0.5503	(-1.074, -0.5524)
	Cos(2*pi*t/24)	-1.447	(-2.502, -1.427)	-0.2693	(-1.035, -0.2668)
	Cos(4*pi*t/24)	-0.2851	(-0.8649, -0.2742)	0.1037	(-0.3165, 0.1049)
Male Indicator Interactions	Sin(2*pi*t/24)	0.3037	(0.0426, 0.3086)	0.2977	(-0.1330, 0.3036)
	Sin(4*pi*t/24)	0.3416	(0.1454, 0.3418)	0.1131	(-0.1049, 0.1127)
	Cos(2*pi*t/24)	0.1152	(-0.3719, 0.1032)	0.3879	(0.0652, 0.3855)
	Cos(4*pi*t/24)	0.0955	(-0.1537, 0.0889)	-0.0759	(-0.2826, -0.0763)
Age Interactions	Sin(2*pi*t/24)	0.0026	(-0.0088, 0.0025)	0.0108	(-0.0118, 0.0116)
	Sin(4*pi*t/24)	0.0024	(-0.0064, 0.0020)	0.0144	(0.0030, 0.0146)
	Sin(6*pi*t/24)	-0.0063	(-0.0093, -0.0062)	0.0127	(0.0095, 0.0128)
	Cos(2*pi*t/24)	-0.0034	(-0.0307, -0.0032)	-0.0062	(-0.0188, -0.0062)
	Cos(4*pi*t/24)	0.0013	(-0.0123, 0.0012)	0.0093	(-0.0007, 0.0093)
	Cos(6*pi*t/24)	0.0084	(0.0041, 0.0086)	0.0011	(-0.0021, 0.0012)
Part-Time Indicator Interactions	Sin(2*pi*t/24)	-1.232	(-1.948, -1.217)	-0.2844	(-1.391, -0.2618)
	Sin(4*pi*t/24)	-0.2684	(-0.8433, -0.2492)	0.5054	(-0.1222, 0.5034)
	Cos(2*pi*t/24)	0.1918	(-1.323, 0.2485)	1.307	(0.4414, 1.2943)
	Cos(4*pi*t/24)	0.0105	(-0.7837, 0.0346)	0.3018	(-0.3227, 0.3025)
High Inc. HH Indicator Interactions	Sin(2*pi*t/24)	-0.0796	(-0.3313, -0.0799)	-0.5753	(-1.002, -0.5713)
	Sin(4*pi*t/24)	-0.1613	(-0.3490, -0.1654)	-0.2843	(-0.4918, -0.2812)
	Cos(2*pi*t/24)	-0.0900	(-0.5749, -0.0860)	-0.3883	(-0.6743, -0.3867)
	Cos(4*pi*t/24)	0.0042	(-0.2509, 0.0086)	0.1498	(-0.0512, 0.1497)
HH Size Interactions	Sin(2*pi*t/24)	-0.0429	(-0.1264, -0.0414)	0.0692	(-0.0649, 0.0674)
	Sin(4*pi*t/24)	0.0102	(-0.0561, 0.0107)	0.0487	(-0.0195, 0.0476)
	Cos(2*pi*t/24)	0.1341	(-0.0046, 0.1338)	0.0721	(-0.0194, 0.0715)
	Cos(4*pi*t/24)	-0.0076	(-0.0854, -0.0075)	0.0400	(-0.0346, 0.0417)
No. Other Tours Interactions	Sin(2*pi*t/24)	-0.3042	(-0.4990, -0.3026)	0.7399	(0.4726, 0.7449)
	Sin(4*pi*t/24)	-0.0425	(-0.1789, -0.0423)	0.1729	(0.0112, 0.1751)
	Cos(2*pi*t/24)	-0.0825	(-0.3842, -0.0778)	-0.1693	(-0.3740, -0.1698)
	Cos(4*pi*t/24)	-0.0384	(-0.1981, -0.0420)	-0.0595	(-0.1980, -0.0554)
Travel Distance Interactions	Sin(2*pi*t/24)	0.0175	(0.0059, 0.0172)	-0.0089	(-0.0307, -0.0091)
	Sin(4*pi*t/24)	0.0032	(-0.0053, 0.0033)	0.0023	(-0.0064, 0.0023)
	Cos(2*pi*t/24)	0.0381	(0.0208, 0.0386)	-0.0028	(-0.0141, -0.0026)
	Cos(4*pi*t/24)	0.0225	(0.0125, 0.0226)	0.0050	(-0.0047, 0.0051)
CBD Dest. Indicator Interactions	Sin(2*pi*t/24)	-0.2002	(-0.6283, -0.1903)	-1.290	(-1.998, -1.299)
	Sin(4*pi*t/24)	-0.1589	(-0.4452, -0.1633)	-0.4269	(-0.8165, -0.4136)
	Cos(2*pi*t/24)	0.6770	(-0.0066, 0.6754)	-0.3724	(-1.009, -0.3411)
	Cos(4*pi*t/24)	0.4269	(0.0048, 0.4291)	0.2123	(-0.1545, 0.2189)

Table 1 (Cont'd): Model Estimation Results

Variable	Mean Estimate	95% Interval
σ_{a1}^2	1.278	(0.8876, 1.225)
σ_{aJ}^2	1.839	(0.2227, 1.581)
σ_{r1}^2	4.459	(3.153, 4.359)
σ_{rJ}^2	1.784	(0.2363, 1.588)
λ_a	0.7442	(0.7257, 0.7446)
λ_r	0.7335	(0.7127, 0.7343)
λ_d	0.8039	(0.7971, 0.8046)
τ_{ar}	0.0512	(0.0014, 0.0483)
τ_d	0.0295	(0.0018, 0.0271)
$\mu_{1,full}$	9.892	(9.750, 9.878)
$\mu_{1,part}$	10.17	(9.798, 10.13)
$\mu_{2,full}$	-0.0814	(-0.1064, -0.0785)
$\mu_{2,part}$	-0.0881	(-0.1363, -0.0817)

405

406 Implied median values of travel time (VOTTs) for the model are \$5.97/hour and \$6.76/hour for arrival
407 and return journeys (with much higher mean VOTTs, at \$19.85/hour and \$16.07/hour, respectively).

408 Implied median values of reliability (VORs) are \$9.95 and \$5.81 per hour of travel time's standard
409 deviation on the home-to-work journey and work-to-home journey, respectively. (Mean VOR estimates
410 are \$13.47 and \$7.17 per hour.)

411

412 Of course, the effects of these variables also depends on the variability in them. For arrival time choice,
413 it turns out that reliability is more practically significant for the home-to-work journey than is average
414 travel time. This makes sense, since many workers are somewhat constrained in their working hours.
415 There also is an incentive for leaving a buffer period, to ensure arrival at or before work is scheduled to
416 begin. Since it may be more acceptable to arrive 10 minutes early than to arrive 10 minutes late, many
417 may depart from home earlier, rather than later.⁴ However, on the return journey, average travel times
418 are more practically significant. One should note, however, that these VOTT and VOR estimates are
419 context-specific (for activity scheduling), and may not be valid for other choice contexts (e.g., mode or
420 route choice) or under different network variable imputation assumptions.

421

422 5.1 Effects of Individuals' Characteristics

423

424 To understand the effects of time-invariant covariates, the "average" sample individual was assumed
425 (i.e., the sample-average value of each covariate was used); and covariate values were varied one at a
426 time. Figure 1 shows density profiles to illustrate the effect each covariate has on predictive densities of
427 the arrival time at work. Note that time-varying variable effects were omitted here, to highlight the
428 effects of each attribute.

429

430

⁴ Small et al. (1999) estimated the marginal costs of early arrival to rise with time, from about \$0.028/min at 5 minutes early, up to about \$0.128/min at 15 minutes early. The marginal cost of late arrival, however, was estimated to be 2.5 to 11 times greater, at \$0.31/min.

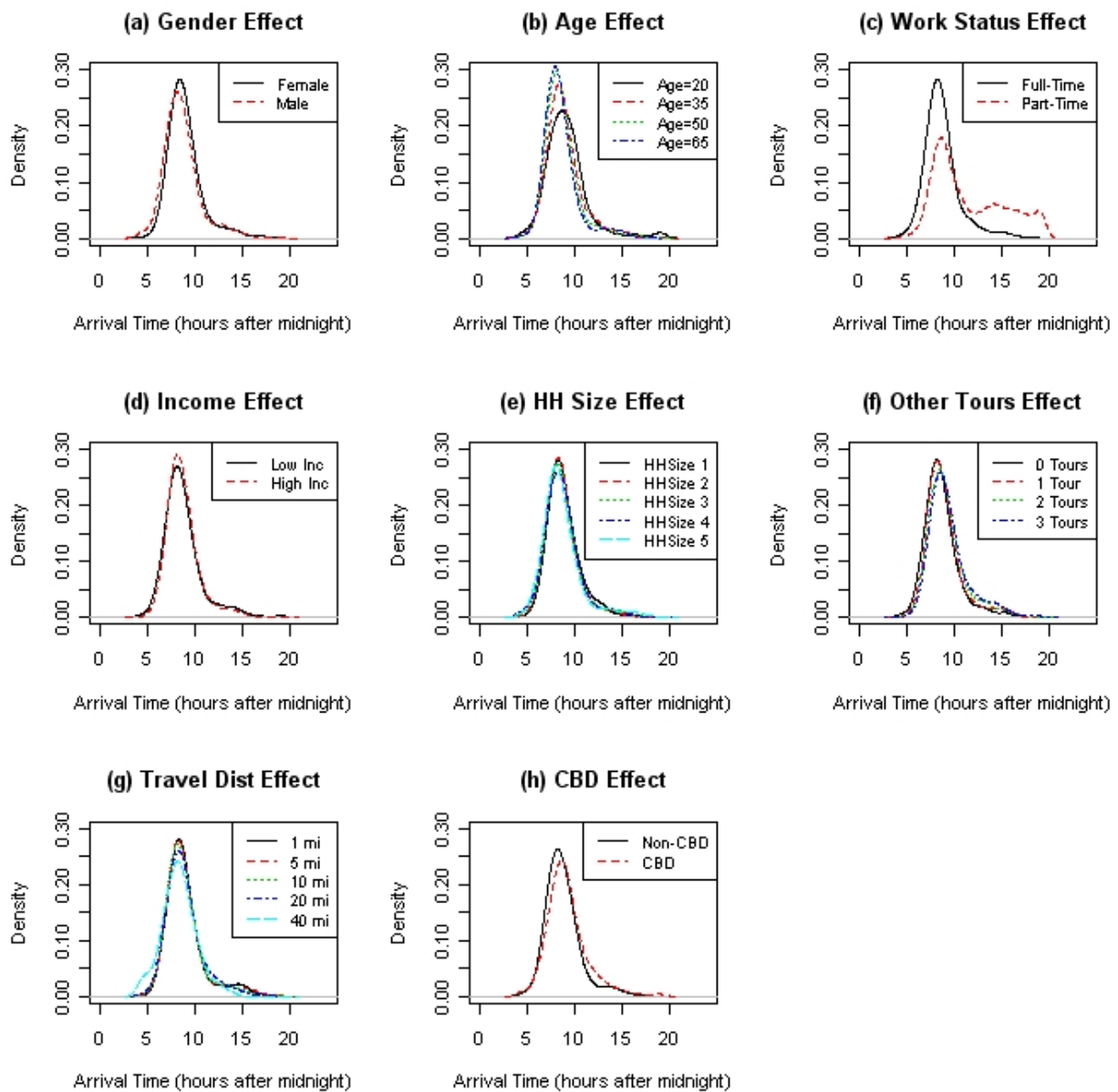


Figure 1: Predicted Arrival Time Density Profiles for Individuals with Different Attributes

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Predictive densities (of systematic utility for work arrival time choice) peak near the AM peak period, as expected. Effects of gender, household income, household size, travel distance, and CBD appear rather small (Figures 1a, 1d, 1e, 1g, and 1h), though in line with expectations. For instance, males, those from larger households, and those with longer travel distances tend to arrive earlier, all else equal. The household size effect can, in some sense, be viewed as a proxy for the number of children, and those with children may have obligations such as dropping off children in the morning. Those with longer travel distances may be arriving earlier on average because they need to leave extra buffer time to be sure to arrive at work on time (since longer distances are associated with larger travel time variances) and/or get started earlier in order to arrive home at a reasonable hour, at the end of a long work day. Individuals from high-income households may have more flexibility in work start times, thus explaining why such individuals tend to arrive a bit later, *ceteris paribus*. Not surprisingly, older individuals (Figure

445 1b) tend to arrive earlier for work, while part-time worker status (Figure 1c) and added tours (Figure 1f)
446 both tend to make later departure times more desirable. These results seem reasonable, since part-
447 time workers often do not work full 8-hour days and those with additional engagements are less likely to
448 be working typical hours.

449
450 Figure 2 shows return time predictive densities for variations in each variable. Males are predicted to
451 return slightly later than females (Figure 2a), and arrive slightly earlier (Figure 1a), on average, so their
452 work durations tend to be slightly longer (by about 20 to 30 minutes). Maybe men are more likely to
453 work overtime than women, and/or females are more likely to have other responsibilities, such as
454 dropping children off at and picking them up from school and child care facilities.

455
456 Older individuals are predicted to return earlier than younger ones (Figure 2b), which is not so surprising
457 given that they are predicted to arrive earlier, on average (Figure 1b). Interestingly, part-time workers'
458 return time profiles (Figure 2c) mimic their arrival time profiles (Figure 1c), with return times shifted to
459 later hours, of course. This is very reasonable considering that such workers may have very different
460 work scheduling constraints, as compared to full-time workers. While household size has little effect on
461 arrival times (Figure 1e) and does not appear to shift return times (Figure 2e), it appears to add
462 uncertainty in return time choice. The presence of additional tours has very important effects on a
463 worker's return time (Figure 2f). In particular, such individuals are predicted to return from work much
464 earlier (about 45 to 90 minutes per additional tour, on average), as the number of such additional tours
465 increases. Since these workers obviously have other scheduling considerations for the day, this seems
466 very reasonable. As with travel distance's limited effect on arrival times, its effect on return times is not
467 substantial (Figure 2g). Finally, the effect of traveling to a workplace in the central business district
468 (CBD) is to push return times later in the day (Figure 2h), consistent with these workers' later arrival
469 times (Figure 1h). Perhaps CBD workers enjoy occupations with later start times. Overall, covariates'
470 effects appear reasonable, though somewhat limited in magnitude.

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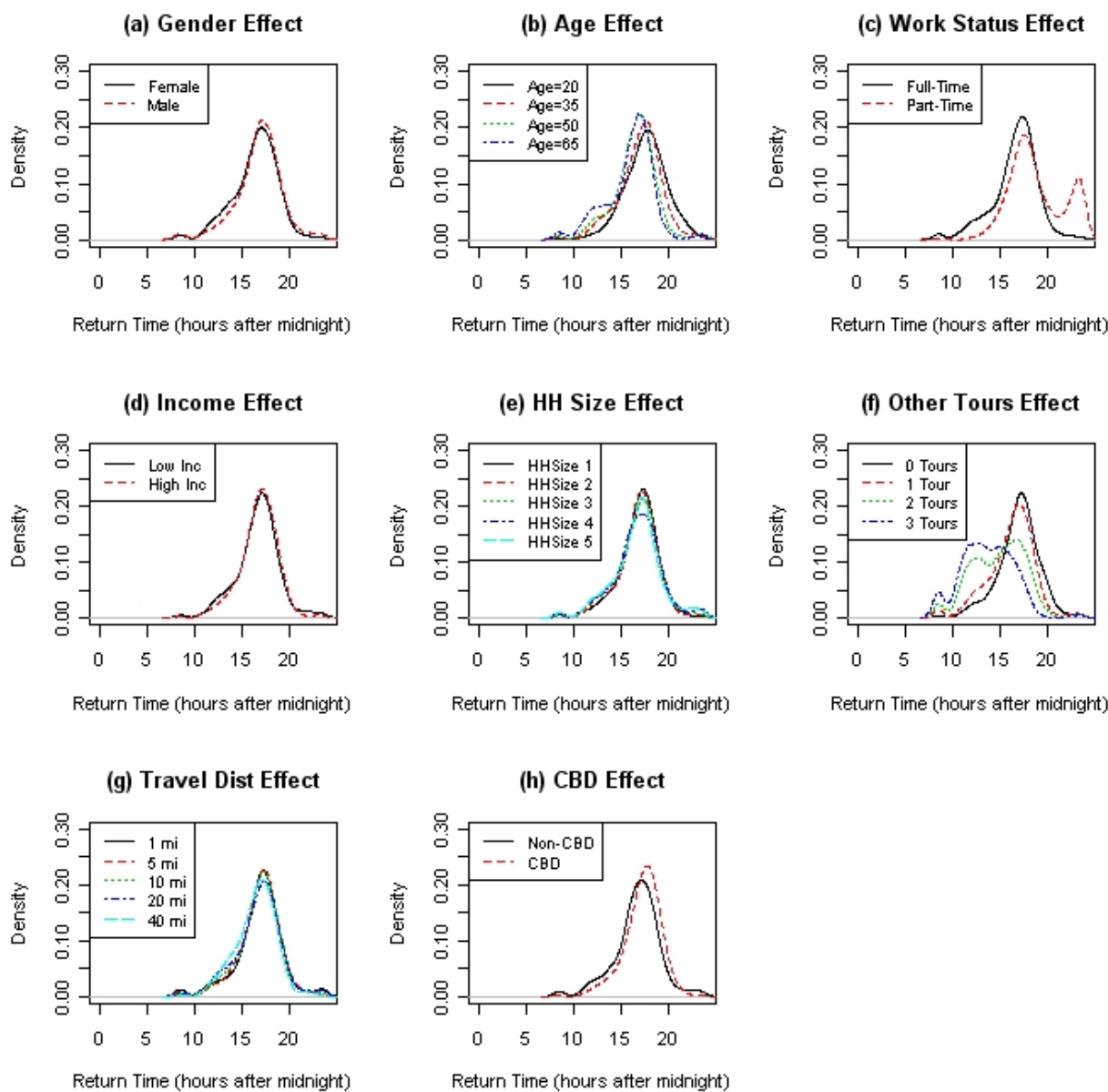


Figure 2: Predicted Return Time Density Profiles for Individuals with Different Attributes

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5.2 Out-of-Sample Predictions

To better appreciate the predictive ability of the BVMNP model, relative to a simple joint-choice multinomial logit (MNL) model, out-of-sample prediction was performed, using a 20% random sample. In the case of the MNL, each choice alternative represents the arrival and return time alternative pair – in contrast to the BVMNP model, which represents arrival times and return times as distinct choices. The MNL model was estimated using BIOGEME software and employed 50 randomly chosen alternatives from the set of all 621 joint choice alternatives along with the chosen alternative⁵. Since the MNL model

⁵ McFadden (1978) showed that one can use a simple random sample of alternatives for MNL estimation and still obtain consistent parameter estimates.

483 represents arrival and return time choice jointly, additional utility components related to alternatives'
484 duration (equal to the return time minus arrival time) and its squared value were included in the model,
485 similar to Popuri et al.'s (2008) specification. For consistency with the BVMNP model's duration
486 components, the sample was segmented by full-time workers with no additional tours for the day and
487 all other workers (i.e., part-time workers and those with additional tours). Since the MNL model is
488 estimated using classical techniques, the predictive likelihood is simply a fixed value.

489
490 For the BVMNP model (as with any MNP), predictive likelihoods are difficult to compute, due to open-
491 form likelihood expressions. Instead, using random parameter draws from the posterior, utilities were
492 drawn from their corresponding distribution for each individual, taking the maximum utilities to signify
493 the chosen alternative. The probabilities of accurate arrival- and departure-time slot prediction were
494 then averaged over all individuals.

495
496 It turns out that predictive accuracies of the BVMNP model are clearly superior to the MNL. In fact, the
497 BVMNP specification beats the MNL nearly 99% of the time. This suggests the BVMNP specification is
498 superior in terms of model fit to the MNL. In the following section, several toll policy simulations are
499 examined using both specifications.

500

501 **5.3 Policy Simulations**

502

503 This section examines the consumer surplus (CS) and predicted departure time distribution changes
504 under each of three toll-policy simulations. In the first, it is assumed that \$0.15/mile tolls are assessed
505 on all roads during the peak periods and that these result in peak-period travel time *delay* reductions of
506 50%. In the second, the same tolls are assessed, but peak-period delay reductions are assumed to be
507 just 10%. In the final simulation, \$0.30/mile peak-period tolls are assumed to reduce peak period delays
508 by 50%. Note that a 50% delay reduction is not the same as a 50% travel time reduction. Delay is
509 measured in relation to free-flow travel time. Thus, routes with no delay during peak periods do not
510 benefit from the toll policies. The simulations were performed using the estimation sample data for
511 those traveling by auto mode only (since non-auto mode users would be largely unaffected by toll
512 policies), and 1,000 random draws from the collection of posterior draws were employed (with the same
513 1,000 random draws used in each policy simulation). Since the MNL model was not estimated using
514 Bayesian methods, its CS changes represent point estimates, rather than the distributional estimates
515 that emerge from the BVMNP model.

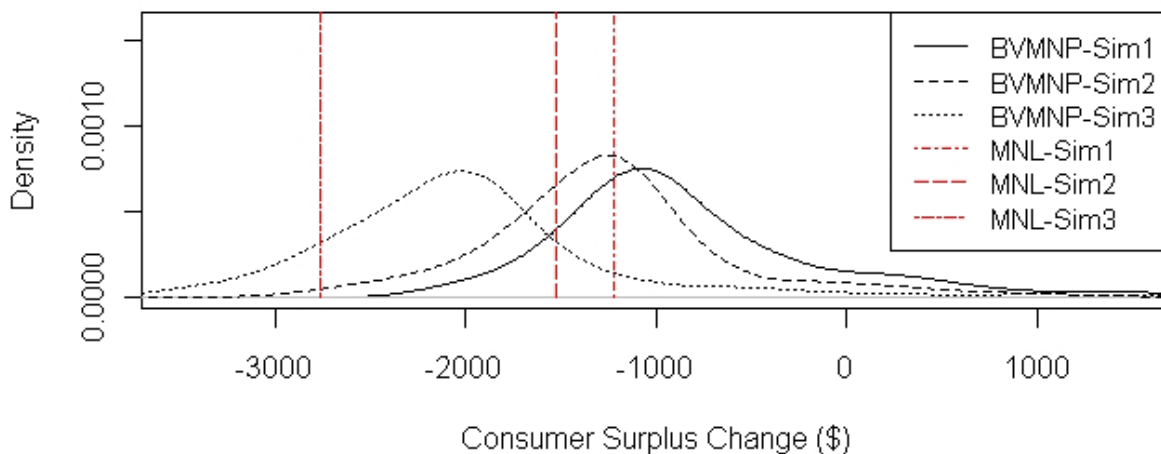
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517 Figure 3 shows the distribution of CS change (measured as the difference in CS between tolling and
518 status quo simulations) for the three tolling policy simulations under the MNL and BVMNP
519 specifications. Average estimates of CS change per traveler were -\$0.90 and -\$1.49 for simulation 1
520 under the BVMNP and MNL specifications, respectively, -\$1.51 and -\$1.85 for simulation 2, and -\$2.41
521 and -\$3.36 for simulation 3. Under both model specifications, Simulation 1's CS changes are estimated
522 to be least negative, not surprisingly since its combination of tolls and delay reductions should offer the
523 greatest value to travelers. In addition, both models predict the CS change under tolling simulation 3 to
524 be more than twice as negative as simulation 1, as expected, since delay reductions are identical for the
525 two simulations, but tolls are twice as large in simulation 3.

526

527 Based on the differences between simulations 1 and 2 under both model specifications, it appears that
528 the peak period delay reduction does have a significant effect on CS change. Toll under these
529 simulations are identical, but peak travel delay is reduced by 40% more in simulation 1 as compared to
530 simulation 2. The most notable difference between the two models here is the magnitude of CS change,

531 which is estimated to be much lower for the MNL than for the BVMNP. This could be because the
532 BVMNP model recognizes the similarities between alternatives near peak periods and peak periods (via
533 error term correlations). In other words, peak shoulder slots may not be viewed as poorly by travelers
534 under the BVMNP specifications, when compared to the MNL, where correlations do not exist. While CS
535 change is important for scenario evaluations and policymaking, it is also important to understand tolls'
536 effects on travelers' scheduling choices.
537



538
539 Figure 3: Consumer Surplus Change Distributions Under Toll Policy Simulations

540
541 To appreciate the tolls' effects on traveler behavior, Figure 4 illustrates simulated aggregate predictive
542 arrival and return time densities for the two models under each scenario. Examining these distributions,
543 it is immediately clear that the MNL specification implies that workers are rather non-responsive to peak
544 tolling policies, while much larger scheduling shifts emerge under the BVMNP specification.
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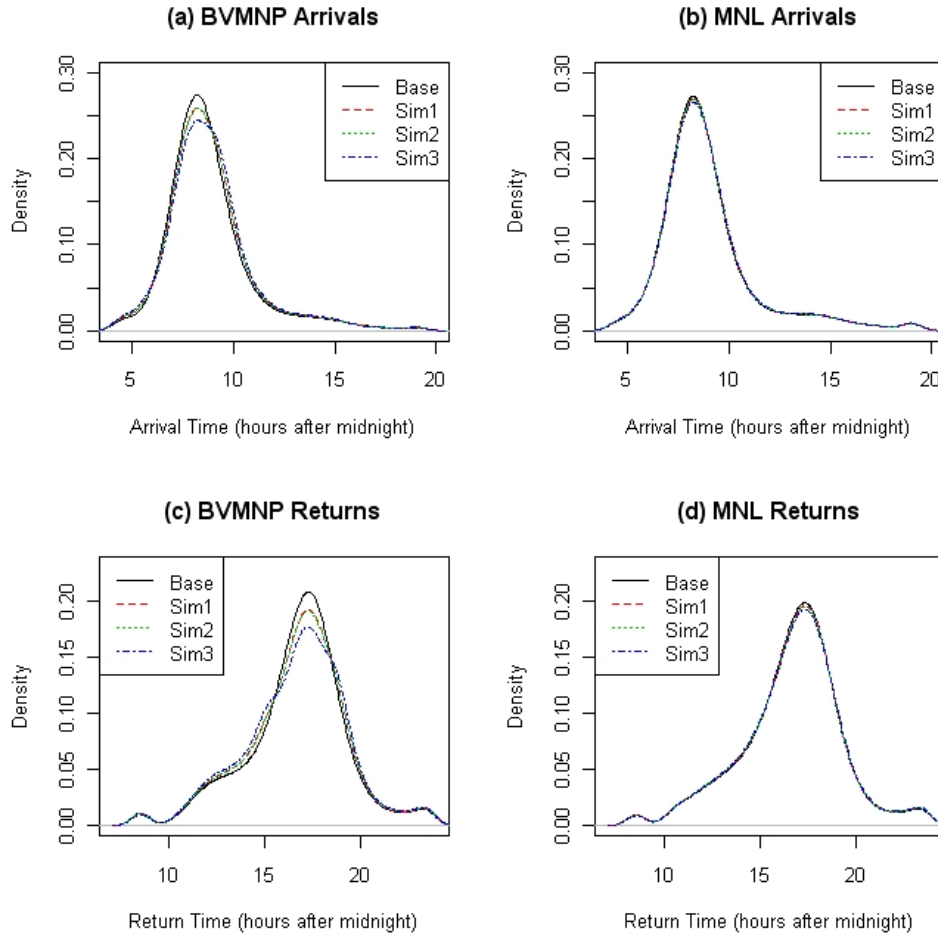


Figure 4: Arrival and Return Time Predictive Densities Under Toll Policy Simulations

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To further examine differences in the two models, three time-of-day periods were examined here: an off-peak period (before 5 am or after 10 am for arrivals and before 2:30 pm or after 7:30 pm for returns), a shoulder peak period (5 to 6 am or 9 to 10 am for arrivals and 2:30 to 3:30 pm or 6:30 to 7:30 pm for returns), and the peak period (6 to 9 am for arrivals and 3:30 to 6:30 pm for returns). Given that the simulated tolls are only applied during peaks, one expects shoulder periods to experience a relatively large increase in shares, as compared to off-peak periods (i.e., before 5 am and after 10 am for arrivals and before 2:30 pm and after 7:30 pm for returns). Under the MNL specification, percentage changes for off-peak and shoulder periods are similar in magnitude for arrivals and returns and for each toll policy simulation, highlighting the MNL's independence of irrelevant alternatives assumption. The BVMNP specification, on the other hand, exhibits percentage changes more in line with expectations. The BVMNP predicts peak-period travelers to shift more toward shoulder periods, with the greatest shoulder period shifts under simulation 3, not surprisingly. Of course, this is due to the correlations offered under the BVMNP specification.

6. CONCLUSIONS

Better methods for modeling travelers' tour scheduling choices are clearly needed. This paper develops and applies a bivariate multinomial probit (BVMNP) model as a reasonable option in the context of tour

568 scheduling. Here, work-tour scheduling was found to be most influenced by age (with older individuals
569 arriving and returning from work earlier in the day), worker status (with part-time worker schedules
570 shifted to later times-of-day), and the number of travel tours undertaken by the worker (with those
571 having additional tours arriving slightly later and returning from work much earlier), each of which
572 seems reasonable.

573
574 Empirical evidence suggests that the BVMNP performs better than a relatively straightforward, and
575 standard, joint MNL model of all paired timing choices. In addition, the BVMNP model offers more
576 reasonable scheduling predictions under various tolling policy simulations. While the MNL predicted
577 rather small changes in the number of peak period travelers, the BVMNP predicted much more
578 substantial peak-period travel reductions. In addition, the BVMNP consistently predicted relatively large
579 share increases for peak shoulder periods (consistent with expectations), whereas MNL predictions for
580 peak shoulders were generally similar in magnitude to off-peak period share increases.

581
582 Bayesian techniques are particularly advantageous in estimating the BVMNP model, where conditional
583 posterior distributions were derived for latent utility variables, covariance components, and utility
584 function parameters separately. Bayesian estimation also provides draws from the multivariate
585 posterior distribution of all parameters. In terms of risk and uncertainty analysis (which is particularly
586 important for toll road analyses), posterior draws offer a natural setting for capturing such uncertainty
587 in demand modeling and other systems.⁶ The scenario analyses provided in this paper illustrate how
588 uncertainty passes through the model into welfare estimates.

589
590 While great strides in activity-based travel demand modeling have been made in recent years, time-of-
591 day modeling remains a key weakness of most model systems. Due to the very large number of
592 alternatives one must typically consider, a major difficulty in tour scheduling models is how to capture
593 correlation across alternatives, since one does not expect independence across such similar alternatives.
594 The BVMNP model offers researchers and analysts the ability to capture such correlations in a
595 meaningful way, while retaining a random utility framework. Of course, more research and
596 experimentation would be needed to fully appreciate the relative merits and limitations of the model.

597
598

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600

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604

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⁶ Capturing uncertainty in model inputs is also important for risk analysis (see, e.g., Lemp and Kockelman 2009).

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